

IMPULSIVE STOCHASTIC DIFFERENTIAL EQUATIONS INVOLVING HILFER FRACTIONAL DERIVATIVES

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Abstract

In this paper, we study the existence of mild solutions of Hilfer fractional stochastic differential equation with impulses driven by sub-fractional Brownian motion. The results are obtained by using Burton-Kirk's fixed point theorem. In the end, an example is given to illustrate the obtained results.

1. Introduction

Differential equations and inclusions with fractional derivatives have recently proved to be strong tools in the modeling of many phenomena in various fields of engineering, economics, physics, biology, ecology, aerodynamics and fluid dynamic traffic models [6, 26, 28, 30]. For some fundamental results in the theory of differential equations involving Caputo and Riemann-Liouville fractional derivatives, please see [1, 2, 24, 32, 33, 34, 41] and the references therein. Since Hilfer [18] proposed the generalized Riemann-Liouville fractional derivative, there has been some interest in studying differential equations involving Hilfer fractional derivatives (see [10, 11, 20] and the references therein). Recently, considerable attention has been given to the existence of solutions of initial and boundary value problems for fractional differential equations with Hilfer fractional derivative [5, 35, 36]. Jaiswal and

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where $D_{0+}^{\alpha,\beta}$ is the generalized Hilfer fractional derivative of order $\alpha \in (0, 1)$, $\beta \in [0, 1]$, $x(\cdot)$ takes value in a real separable Hilbert space U with inner product (\cdot, \cdot) and norm $\|\cdot\|$, A is the infinitesimal generator of strongly continuous semigroup of bounded linear operator $\{T(t)\}_{t \geq 0}$. S_Q^H is an Q -sub-fBm with Hurst parameter $H \in (\frac{1}{2}, 1)$, and $I_0^{1-\gamma}$ is the fractional integral of orders $1 - \gamma$ ($\gamma = \alpha + \beta - \alpha\beta$). The impulses times satisfy $0 = t_0 = s_0 < t_1 \leq s_1 < t_2 \leq \dots < t_m \leq s_m < t_{m+1} = T$, for $t > 0$. x_t means a segment solution which is defined by $x(\cdot, \cdot) : (-\infty, T] \times \Omega \rightarrow U$, and for any $t \geq 0$, $x_t(\cdot, \cdot) : (-\infty, 0) \times \Omega \rightarrow U$ is given by $x_t(\theta, \omega) = x(t + \theta, \omega)$, $\theta \in (-\infty, 0]$, $\omega \in \Omega$. $\mathcal{D}_{\mathcal{F}_T}^\gamma$ is defined as

$$\mathcal{D}_{\mathcal{F}_T}^\gamma = \left\{ x : (-\infty, T] \times \Omega \rightarrow U; x|_{J_k} \in C(J_k; U), t^{1-\gamma}x(t) \in \mathcal{D}_{\mathcal{F}_T}, \right. \\ \left. k = 1, \dots, m, \right.$$

with the norm

$$\|x\|_{\mathcal{D}_{\mathcal{F}_T}^\gamma} = \|\phi\|_{\mathcal{D}_{\mathcal{F}_0}} + \left(\sup_{0 \leq t \leq T} \mathbb{E} \|t^{1-\gamma}x(t)\|^2 \right)^{\frac{1}{2}},$$

and $\phi \in \mathcal{D}_{\mathcal{F}_0}$, where $J_k = (s_k, t_{k+1}]$, $k = 1, \dots, m$.

If the space $\mathcal{D}_{\mathcal{F}_t}$ is the space formed by all \mathcal{F}_t -adapted measurable square integrable \mathcal{H} -valued stochastic process $\{x(t) : t \in [0, T]\}$ with the norm $\|x\|_{\mathcal{D}_{\mathcal{F}_t}}^2 = \sup_{t \in [0, T]} \mathbb{E} \|x(t)\|^2$, then $(\mathcal{D}_{\mathcal{F}_t}, \|\cdot\|_{\mathcal{D}_{\mathcal{F}_t}})$ is a Banach space.

$\mathcal{D}_{\mathcal{F}_0}$ denotes the family of all almost surely bounded \mathcal{F}_0 -measurable, and \tilde{D} -valued random variables. $\tilde{D} = D((-\infty, 0], U)$ denotes the family of all right piecewise continuous functions with left-hand limit ϕ from $(-\infty, 0]$ to U , with the norm

$$\|\phi\|_t = \sup_{-\infty < \theta \leq t} \|\phi(\theta)\|.$$

We assume in the sequel that $X(t, x_t) : J \times U \rightarrow U$, such that $X(t, x_t) = \phi(0) - g(t, x_t)$, $g : J \times \mathcal{D}_{\mathcal{F}_T}^\gamma \rightarrow U$ and $f : J \times \mathcal{D}_{\mathcal{F}_T}^\gamma \rightarrow U$, $h_k \in (t_k, s_k] \times \mathcal{D}_{\mathcal{F}_T}^\gamma \rightarrow U$ for all $k = 1, \dots, m$. $\sigma : J \times \mathcal{D}_{\mathcal{F}_T}^\gamma \rightarrow L_Q^0(K, H)$.

This paper is structured as follows. In Section 2 we introduce some notations, definitions and preliminary facts about sub-fractional Brownian motion and fractional calculus which are useful throughout the paper. In

Section 3 we prove the existence of $\mathcal{D}_{\mathcal{F}_T}^\gamma$ -mild solutions for problem (1). Finally an example is given to illustrate our result in Section 5.

2. Preliminaries

In this section, we give some basic definitions, notations, lemmas and some basic facts about sub-fractional Brownian motion and fractional calculus.

Definition 2.1 (*Cylindrical Sub-Fractional Brownian Motion*). Let \mathcal{K} be a separable Hilbert space. A continuous, zero mean, \mathcal{K} -valued Gaussian process $(S_I^H(t), t \geq 0)$ is said to be cylindrical sub-fractional Brownian motion with Hurst parameter $H \in (0, 1)$ if its covariance is given by

$$E \langle k, S_I^H(s) \rangle \langle k', S_I^H(t) \rangle = \langle k, k' \rangle \left[s^{2H} + t^{2H} - \frac{1}{2} \left[(s+t)^{2H} + |t-s|^{2H} \right] \right]$$

for all $s, t \in \mathbb{R}^+$ and $k, k' \in \mathcal{K}$.

Definition 2.2. Let Q be a non-negative, self-adjoint bounded linear operator that is not nuclear. Then, a cylindrical sub-fractional Brownian motion is defined by the formal series

$$S_I^H(t) = \sum_{n=1}^{\infty} S_n^H(t) e_n \quad t \geq 0;$$

where $\{S_n^H(t)\}_{n=1}^{\infty}$ is a sequence of independent, real valued standard sub-fractional Brownian motion with Hurst parameter $H \in (0, 1)$ and $\{e_n\}_{n=1}^{\infty}$ being a complete orthonormal basis in the Hilbert space \mathcal{K} .

Let $(\mathcal{H}, \|\cdot\|_{\mathcal{H}}, (\cdot, \cdot)_{\mathcal{H}})$ and $(\mathcal{K}, \|\cdot\|_{\mathcal{K}}, (\cdot, \cdot)_{\mathcal{K}})$ being the separable Hilbert spaces. The notation $\mathcal{C}(J, \mathcal{H})$ stands for the Banach space of continuous functions from J to \mathcal{H} with supremum norm, i.e., $\|x\|_J = \sup_{t \in J} \|x(t)\|$ and $L^1(J, \mathcal{H})$ denotes the Banach space of functions $x : J \rightarrow \mathcal{H}$ which are Bochner integrable normed by $\|x\|_{L^1} = \int_0^b \|x(t)\| dt$, for all $x \in L^1(J, \mathcal{H})$. A measurable function $x : J \rightarrow \mathcal{H}$ is Bochner integrable if and only if $\|x\|$ is Lebesgue integrable.

Let $(\Omega, \mathcal{F}, \mathbb{P})$ be a complete probability space equipped with a normal filtration $\{\mathcal{F}_t\}_{t \geq 0}$ satisfying the usual conditions (i.e., right continuous and \mathcal{F}_0 containing all \mathbb{P} -null sets).

Definition 2.3. The sub-fractional Brownian motion (sub-fBm in short) with Hurst parameter $H \in (0, 1)$ is a mean zero Gaussian process $S^H = \{S_t^H : t \geq 0\}$ with $S_H^0 = 0$ and the covariance

$$C_H(t, s) = \mathbb{E} [S_t^H S_s^H] = s^{2H} + t^{2H} - \frac{1}{2} [(s+t)^{2H} + |t-s|^{2H}], \quad (2)$$

for all $s, t \geq 0$.

For $H = \frac{1}{2}$, S^H coincides with the standard Brownian motion B . S^H is neither semimartingale nor a Markov process when $H \neq \frac{1}{2}$. The sub-fBm S^H has properties analogous to those of fBm (self-similarity, long-range dependence, Hölder paths), but it does not have stationary increments. For more details on sub-fBm, we refer to [7, 31, 29].

The sub-fractional Brownian motion satisfies the following estimates:

$$[(2 - 2^{2H-1}) \wedge 1] |t-s|^{2H} \mathbb{E} |S^H(t) - S^H(s)|^2 \leq [(2 - 2^{2H-1}) \wedge 1] |t-s|^{2H}. \quad (3)$$

Thus, Kolmogorov's continuity criterion implies that sub-fBm is Hölder continuous of order γ for any $\gamma < H$ on any finite interval. Therefore, if y is a stochastic process with Hölder continuous trajectories of order $\beta > 1 - H$ then the pathwise Riemann-Stieltjes integral $\int_0^b y_t(\omega) dS^H(t)(\omega)$ exists for all $b \geq 0$. In particular, if $H > \frac{1}{2}$, the pathwise integral $\int_0^b f'(S_t^H) dS_t^H$ exists for all $f \in C^2(\mathbb{R})$, and

$$f(S_b^H) - f(0) = \int_0^b f'(S_t^H) dS_t^H. \quad (4)$$

However, when $H < \frac{1}{2}$ the pathwise Riemann-Stieltjes integral

$\int_0^b f'(S_t^H) dS_t^H(\omega)$ does not exist. For more details, we refer the reader to [29][38][39].

Now we aim at introducing the Wiener integral with respect to one dimensional sub-fBm S^H . Fix a time interval $[0, b]$. We denote by Λ the linear space of \mathbb{R} -valued step functions on $[0, b]$, that is, $y \in \Lambda$ if

$$y(t) = \sum_{i=1}^{n-1} x_i 1_{[t_i, t_{i+1}]}(t),$$

where $t \in [0, b]$, $x_i \in \mathbb{R}$ and $0 = t_1 < t_2 < \dots < t_n = b$. For $y \in \Lambda$ we define its Wiener integral with respect to S^H as

$$\int_0^b y(s) dS_Q^H(s) = \sum_{i=1}^{n-1} x_i (S_{t_{i+1}}^H - S_{t_i}^H).$$

Let \mathcal{H}_{S^H} be the canonical Hilbert space associated to the sub-fBm S^H , that is, \mathcal{H}_{S^H} is the closure of the linear span Λ with respect to the scalar product

$$(1_{[0,t]}, 1_{[0,s]})_{\mathcal{H}_{S^H}} = C_H(t, s).$$

We know that the covariance of sub-fBm can be written as

$$\mathbb{E} [S_t^H S_s^H] = \int_0^t \int_0^s \eta_H(u, v) dudv = C_H(t, s), \tag{5}$$

where $\eta_H(u, v) = H(2H - 1) (|u - v|^{2H-2} - (u + v)^{2H-2})$.

Equation (5) implies that

$$(y, z)_{\mathcal{H}_{S^H}} = \int_0^t \int_0^s y_u z_v \eta_H(u, v) dudv, \tag{6}$$

for any pair step functions y and z on $[0, b]$. Consider the kernel

$$K_H(t, s) = \frac{2^{1-H} \sqrt{\pi}}{\Gamma(H - \frac{1}{2})} s^{3/2-H} \left(\int_0^t (x^2 - s^2)^{H-3/2} ds \right) 1_{[0,t]}(s). \tag{7}$$

By Dzshaparidze and Van Zanten [8], we have

$$C_H(t, s) = c_H^2 \int_0^{t \wedge s} K_H(t, u) K_H(s, u) du \tag{8}$$

where

$$c_H^2 = \frac{\Gamma(1 + 2H)\sin(\pi H)}{\pi}.$$

Then, (8) implies that $C_H(s, t)$ is non-negative definite. Consider the linear operator $K_H^* : \Lambda \rightarrow L^2([0, b])$ defined by

$$(K_H^* y)(s) = c_H \int_s^r y_r \frac{\partial K_H}{\partial r}(r, s) dr.$$

Using (6) and (8) we have

$$\begin{aligned} & (K_H^* y, K_H^* z)_{L^2([0, b])} \\ &= c_H^2 \int_0^b \left(\int_s^b y_r \frac{\partial K_H}{\partial r}(r, s) dr \right) \left(\int_s^b z_u \frac{\partial K_H}{\partial u}(u, s) du \right) ds \\ &= c_H^2 \int_0^b \int_0^b \left(\int_0^{r \wedge u} \frac{\partial K_H}{\partial r}(r, s) \frac{\partial K_H}{\partial u}(u, s) ds \right) y_r z_u dr du \\ &= c_H^2 \int_0^b \int_0^b \frac{\partial^2 K_H}{\partial r \partial u}(u, s) y_r z_u dr du \\ &= H(2H - 1) \int_0^b \int_0^b (|u - r|^{2H-2} - (u + r)^{2H-2}) y_r z_u dr du \\ &= (y, z)_{\mathcal{H}_{\mathcal{S}^H}}. \end{aligned} \tag{9}$$

As a consequence, the operator K_H^* provides an isometry between the Hilbert space $\mathcal{H}_{\mathcal{S}^H}$ and $L^2([0, b])$. Hence, the process W defined by $W(t) := S^H((K_H^*)^{-1}(1_{[0, t]}))$ is a Wiener process, and S^H has the following Wiener integral representation:

$$S^H(t) = c_H \int_0^t K_H(t, s) dW(s)$$

because $(K_H^*(1_{[0, t]}))(s) = c_H K_H(t, s)$. By [8], we have

$$W(t) = \int_0^t Z_H(t, s) dS^H(s),$$

where

$$Z_H(t, s) = \frac{s^{H-1/2}}{\Gamma(3/2 - H)} \left[t^{H-3/2} (t^2 - s^2)^{1/2-H} \right]$$

$$- (H - 3/2) \int_s^t (x^2 - s^2)^{1/2-H} x^{H-3/2} dx \Big] (1_{[0,t]})(s).$$

In addition, for any $y \in \mathcal{H}_{S^H}$,

$$\int_0^b y(s) dS^H(s) = \int_0^b (K_H^* y)(t) dW(t)$$

if and only if $K_H^* y \in L^2([0, b])$.

Also, denote $L^2_{\mathcal{H}_{S^H}}([0, b]) = \{y \in \mathcal{H}_{S^H}, K_H^* y \in L^2([0, b])\}$. Since $H > \frac{1}{2}$, we have by (9) and Lemma 2.1 of [25],

$$L^2([0, b]) \subset L^{\frac{1}{H}}([0, b]) \subset L^2_{\mathcal{H}_{S^H}}([0, b]). \tag{10}$$

Lemma 2.1 ([27]). *For $y \in L^{\frac{1}{H}}([0, b])$,*

$$H(2H - 1) \int_0^b \int_0^b |y_r| |y_u| |u - r|^{2H-2} dr du \leq C_H \|y\|_{L^{\frac{1}{H}}([0,b])},$$

where $C_H = \left(\frac{H(2H-1)}{\beta(2-2H, H-\frac{1}{2})}\right)^{1/2}$, with β denoting the beta function.

Let $L(\mathcal{K}, \mathcal{H})$ denote the space of all bounded linear operators from \mathcal{K} into \mathcal{H} with the usual norm $\|\cdot\|_{L(\mathcal{K}, \mathcal{H})}$. Let $Q \in L(\mathcal{K}, \mathcal{H})$ be a non-negative self-adjoint operator. Denoted by $L^0_Q(\mathcal{K}, \mathcal{H})$ the space of all $\xi \in L(\mathcal{K}, \mathcal{H})$ such that $\xi Q^{\frac{1}{2}}$ is a Hilbert-Schmidt operator. The norm is given by

$$\|\xi\|^2_{L^0_Q(\mathcal{K}, \mathcal{H})} = \|\xi Q^{\frac{1}{2}}\|^2_{HS} = tr(\xi Q \xi^*).$$

Then ξ is called a Q -Hilbert-Schmidt operator from \mathcal{K} to \mathcal{H} . Let $\{S_n^H(t)\}_{n \in \mathbb{N}}$ be a sequence of one-dimensionnal standard sub-fractional Brownian motions mutually independent over $(\Omega, \mathcal{F}, \mathbb{P})$.

Set

$$S_Q^H(t) = \sum_{n=1}^{\infty} S_n^H(t) Q^{\frac{1}{2}} e_n, \quad t \geq 0,$$

where $\{e_n\}_{n \in \mathbb{N}}$ is a complete orthonormal basis in \mathcal{K} .

If Q is a non-negative self-adjoint trace class operator, then the above \mathcal{K} -valued stochastic process $S_Q^H(t)$ is called Q -cylindrical sub-fractional Brow-

nian motion with covariance operator Q .

Lemma 2.2 ([27]). *For any $y : [0, b] \rightarrow L_Q^0(\mathcal{K}, \mathcal{H})$ such that*

$$\sum_{n=1}^{\infty} \|yQ^{\frac{1}{2}}e_n\|_{L^{\frac{1}{H}}([0,b],\mathcal{H})} < \infty$$

holds, and for any $u, v \in [0, b]$ with $u > v$,

$$\mathbb{E} \left\| \int_v^u y(s) dS_Q^H(s) \right\|_{\mathcal{H}}^2 \leq C_H(u-v)^{2H-1} \sum_{n=1}^{\infty} \int_v^u \|y(s)Q^{\frac{1}{2}}e_n\|_{\mathcal{H}}^2 ds.$$

If, in addition,

$$\sum_{n=1}^{\infty} \|y(s)Q^{\frac{1}{2}}e_n\|_{\mathcal{H}}^2 \text{ is uniformly convergent for } t \in [0, b],$$

then

$$\mathbb{E} \left\| \int_v^u y(s) dS_Q^H(s) \right\|_{\mathcal{H}}^2 \leq C_H(u-v)^{2H-1} \int_v^u \|y(s)\|_{L_Q^0(\mathcal{K},\mathcal{H})}^2 ds.$$

We suppose that $\mathcal{F}_t = \sigma\{S_Q^H; 0 \leq s \leq t\}$ is the σ -algebra generated by the \mathcal{K} -valued Q -cylindrical sub-fractional Brownian motion, $\mathcal{F}_b = \mathcal{F}$.

Definition 2.4 ([23]). The fractional integral of order $\alpha > 0$ with the lower limit zero for a function f is defined as

$$I^\alpha f(t) = \frac{1}{\Gamma(\alpha)} \int_0^t \frac{f(s)}{(t-s)^{1-\alpha}} ds, \quad t > 0, \alpha > 0,$$

provided the right-hand side is pointwise defined on $[0, \infty)$, where $\Gamma(\cdot)$ is the gamma function.

Definition 2.5. The Riemann-Liouville fractional derivative of order $\alpha > 0$ $n - 1 < \alpha < n, n \in \mathbb{N}$, is defined as

$${}^{(R-L)}D_{0+}^\alpha f(t) = \frac{1}{\Gamma(n-\alpha)} \left(\frac{d}{dt}\right)^n \int_0^t (t-s)^{n-1-\alpha} f(s) ds,$$

where the function $f(t)$ has absolutely continuous derivative up to order $(n - 1)$.

Definition 2.6 ([18]). The Hilfer fractional derivative of order $0 \leq \alpha \leq 1$ and $0 < \beta < 1$ for a function f is defined by

$$D_{0+}^{\alpha,\beta} f(t) = I_{0+}^{\alpha(1-\beta)} \frac{d}{dt} I_{0+}^{(1-\alpha)(1-\beta)} f(t).$$

Remark 2.1. When $\alpha = 0$, $0 < \beta < 1$, the Hilfer fractional derivative coincides with the classical Riemann-Liouville fractional derivative

$$D_{0+}^{0,\beta} f(t) = \frac{d}{dt} I_{0+}^{1-\beta} f(t) = {}^L D_{0+}^{\beta} f(t).$$

When $\alpha = 1$, $0 < \beta < 1$, the Hilfer fractional derivative coincides with the classical Caputo fractional derivative

$$D_{0+}^{1,\beta} f(t) = I_{0+}^{1-\beta} \frac{d}{dt} f(t) = {}^c D_{0+}^{\beta} f(t).$$

Next we mention an axiomatic definition of the phase space $\mathcal{D}_{\mathcal{F}_0}$ introduced by Hale and Kato.

Definition 2.7. $\mathcal{D}_{\mathcal{F}_0}$ is a linear space of family of \mathcal{F}_0 -measurable functions from $(-\infty, 0]$ into U endowed with a norm $\| \cdot \|_{\mathcal{D}_{\mathcal{F}_0}}$, which satisfies the following axioms:

(A-1) If $x : (-\infty, T] \rightarrow U$, $T > 0$ is such that $y_0 \in \mathcal{D}_{\mathcal{F}_0}$, then for every $t \in [0, T)$ the following conditions hold

(i) $y_t \in \mathcal{D}_{\mathcal{F}_0}$.

(ii) $\| y(t) \| \leq \mathcal{L} \| y_t \|_{\mathcal{D}_{\mathcal{F}_0}}$.

(iii) $\| y_t \|_{\mathcal{D}_{\mathcal{F}_0}} \leq K(t) \sup \{ \| y(s) \| : 0 \leq s \leq t \} + N(t) \| y(0) \|_{\mathcal{D}_{\mathcal{F}_0}}$, where $\mathcal{L} > 0$ is a constant; $K, N : [0, \infty) \rightarrow [0, \infty)$, K is continuous, N is locally bounded and K, N are independent of $y(\cdot)$.

(A-2) : For the function $y(\cdot)$ in (A-1), y_t is a $\mathcal{D}_{\mathcal{F}_0}$ -valued function for $t \in [0, T)$.

(A-3) : The space $\mathcal{D}_{\mathcal{F}_0}$ is complete.

Denote

$$\tilde{K} = \sup \{ K(t) : t \in J \} \text{ and } \tilde{N} = \sup \{ N(t) : t \in J \}.$$

Theorem 2.8 (Banach's Fixed Point Theorem). *Let (X, d) be a complete metric space and let $T : X \rightarrow X$ be a contraction on X . Then T has a unique fixed point $x \in X$ (such that $T(x) = x$).*

Let us define the operators $\{S_{\alpha,\beta}(t) : t \geq 0\}$ and $\{P_\beta(t) : t \geq 0\}$ by

$$\begin{aligned} S_{\alpha,\beta}(t) &= I_{0+}^{\alpha(1-\beta)} P_\beta(t), \\ P_\beta(t) &= t^{\beta-1} T_\beta(t), \\ T_\beta(t) &= \int_0^\infty \beta \theta \Psi_\beta(\theta) T(t^\beta \theta) d\theta; \end{aligned}$$

where

$$\Psi_\beta(\theta) = \sum_{n=1}^{\infty} \frac{(-\theta)^{n-1}}{(n-1)\Gamma(1-n\beta)}, \quad 0 < \beta < 1, \theta \in (0, \infty)$$

is a function of Wright type which satisfies

$$\int_0^\infty \theta^\xi \Psi_\beta(\theta) d\theta = \frac{\Gamma(1+\xi)}{\Gamma(1+\beta\xi)}, \quad \xi \in (-1, \infty).$$

Lemma 2.3 ([11]). *The operators $S_{\alpha,\beta}$ and P_β have the following properties*

i) *For any fixed $t \geq 0$, $S_{\alpha,\beta}(t)$ and $P_\beta(t)$ are bounded linear operators, and*

$$\begin{aligned} \|P_\beta(t)x\|^2 &\leq M \frac{t^{2(\beta-1)}}{(\Gamma(\beta))^2} \|x\|^2 \quad \text{and} \\ \|S_{\alpha,\beta}(t)x\|^2 &\leq M \frac{t^{2(\alpha-1)(1-\beta)}}{(\Gamma(\alpha(1-\beta) + \beta))^2} \|x\|^2. \end{aligned}$$

ii) *$\{P_\beta(t) : t \geq 0\}$ is compact if $\{T(t) : t \geq 0\}$ is compact.*

Remark 2.2. $D_{0+}^{\alpha(1-\beta)} S_{\alpha,\beta}(t) = P_\beta(t)$.

3. Existence of Mild Solution

In this section, we first establish the existence of mild solutions to stochastic differential equations with non-instantaneous impulses driven by a Q -sub-fractional Brownian motion (1). More precisely, we will formulate and prove sufficient conditions for the existence of solutions to (1). In order to establish the results, we make the following hypotheses.

- (H1) The operator A is the infinitesimal generator of a strongly continuous of bounded linear operators $\{S(t)\}_{t \geq 0}$ which is compact for $t > 0$ in \mathcal{H} such that $\|S(t)\|^2 \leq M$ for each $t \in J$, where $J = [0, T]$.
- (H2) The operators $S_{\alpha, \beta}, P_\beta \in D(A)$.
- (H3) The function $f : J \times \mathcal{D}_{\mathcal{F}_T}^\gamma \rightarrow U$ satisfies that:
 $\mathbb{E} \|f(t, \phi_1) - f(t, \phi_2)\|^2 \leq L_f \|\phi_1 - \phi_2\|_{\mathcal{D}_{\mathcal{F}_T}^\gamma}^2$,
 for all $\phi_1, \phi_2 \in \mathcal{D}_{\mathcal{F}_T}^\gamma$, $t \in (s_k, t_{k+1}]$ and $k = 1, \dots, m$.
- (H4) The function $g : J \times \mathcal{D}_{\mathcal{F}_T}^\gamma \rightarrow U$ and there exists a positive number K_g . For $t \in J$, we have
 $\mathbb{E} \|g(t, \phi_1) - g(t, \phi_2)\|^2 \leq K_g \|\phi_1 - \phi_2\|_{\mathcal{D}_{\mathcal{F}_T}^\gamma}^2$, for all $\phi_1, \phi_2 \in \mathcal{D}_{\mathcal{F}_T}^\gamma$, $t \in J$.
- (H5) The function $\sigma : J \times \mathcal{D}_{\mathcal{F}_T}^\gamma \rightarrow L_Q^0$ satisfies that there exists a positive constant L_σ such that
 $\mathbb{E} \|\sigma(t, \phi_1) - \sigma(t, \phi_2)\|_{L_Q^0}^2 \leq L_\sigma \|\phi_1 - \phi_2\|_{\mathcal{D}_{\mathcal{F}_T}^\gamma}^2$, for all $\phi_1, \phi_2 \in \mathcal{D}_{\mathcal{F}_T}^\gamma$, $t \in (s_k, t_{k+1}]$ and $k = 1, \dots, m$.
- (H6) There exist constants $L_{h_k} > 0$, for all $\phi_1, \phi_2 \in \mathcal{D}_{\mathcal{F}_T}^\gamma$, $t \in (t_k, s_k]$ and $k = 1, \dots, m$ such that

$$\mathbb{E} \|h_k(t, \phi_1) - h_k(t, \phi_2)\|^2 \leq L_{h_k} \|\phi_1 - \phi_2\|_{\mathcal{D}_{\mathcal{F}_T}^\gamma}^2$$

and $h_k \in C((t_k, s_k] \times \mathcal{D}_{\mathcal{F}_T}^\gamma, U)$, for all $k = 1, \dots, m$.

Now, we give the definition of mild solutions to our problem.

Definition 2.9. An \mathcal{F}_t -adapted stochastic process $x : (-\infty, T] \rightarrow U$ is said to be an mild solution of (1) if $x_0 = \phi \in \mathcal{D}_{\mathcal{F}_0}$ and

- (i) $\{x_t, t \in J\} \in \mathcal{D}_{\mathcal{F}_T}^\gamma$,
 (ii) $\int_0^t [x_s + g(s, x_s)] ds \in D(A)$, $t \in [0, T]$.

(iii) for each $t > 0$

$$x(t) = \begin{cases} S_{\alpha,\beta}(t) [\phi(0) - g(0, \phi)] + g(t, x_t) \\ + \int_0^t P_\beta(t-s)f(s, x(s))ds \\ + \int_0^t P_\beta(t-s)\sigma(s, x_s)dS_Q^H(s), & \text{for } t \in [0, t_1], \\ h_k(t, x_t), & \text{for } t \in (t_k, s_k]; \\ & k = 1, \dots, m. \\ S_{\alpha,\beta}(t - s_k)h_k(s_k, x_{s_k}) + g(s_k, x_{s_k}) \\ + \int_{s_k}^t P_\beta(t-s)f(s, x_s)ds & \text{for } t \in [s_k, t_{k+1}]; \\ + \int_{s_k}^t P_\beta(t-s)\sigma(s, x_s)dS_Q^H(s) & k = 1, \dots, m. \end{cases} \tag{11}$$

To establish the existence and uniqueness theorem of the mild solution for system (1), we use a Banach fixed point to investigate the existence and uniqueness of solutions for impulsive stochastic differential equations.

Theorem 2.10. *Let (H1)-(H6) hold with $\phi(0) - g(0, \phi) \in \overline{D(A)}$, and*

$$L_0 = \max(\mu_1, \mu_2, \mu_3) < 1,$$

where

$$\mu_1 = 3t_1^{2(\alpha\beta+1)} \left(t_1^{1-\alpha-\beta} K_g + \frac{t_1^{-\alpha} L_f M}{(\Gamma(\beta))^2} + \frac{M L_\sigma t_1^{H-\alpha}}{(\Gamma(\beta))^2} \right),$$

$$\mu_2 = \max_{k=1, \dots, m} 2L_{h_k} T^{2(1-\gamma)},$$

$$\mu_3 = \max_{k=1, \dots, m} \left[\frac{4ML_{h_k}}{\Gamma(\alpha(1-\alpha) + \beta)^2} + 4t^{2(1-\gamma)} K_g + \frac{4t^{2(1-\gamma)} M(t_{k+1} - s_k)^{2(\beta-1)} L_f}{(\Gamma(\beta))^2} + \frac{C_H M L_\sigma t^{2(H-\gamma)+1} (t_{k+1} - s_k)^{2(\beta-1)}}{(\Gamma(\beta))^2} \right].$$

Then for every initial function $\phi \in \mathcal{D}_{\mathcal{F}_0}$ there exists a unique associated mild solution $x \in \mathcal{D}_{\mathcal{F}_T}^\gamma$ of the problem (1).

Proof. The proof is given in several steps. Consider the problem (1)

$$\begin{cases} D_{0+}^{\alpha,\beta} X(t, x_t) = A(t) X(t, x_t) + f(t, x_t) & \text{for } t \in [s_k, t_{k+1}], \\ + \sigma(t, x_t) \frac{dS_Q^H(t)}{dt}, & k = 0, \dots, m, \\ x(t) = h_k(t, x_t), & \text{for } t \in (t_k, s_k], k = 1, 2, \dots, m, \\ (I_0^{1-\gamma} x)(t)|_{t=0} = \phi \in \mathcal{D}_{\mathcal{F}_0}((-\infty, 0], U]. \end{cases}$$

We transform the problem into a fixed point one. Consider the operator $\Phi : \mathcal{D}_{\mathcal{F}_T}^\gamma \longrightarrow \mathcal{D}_{\mathcal{F}_T}^\gamma$ defined by

$$\Phi(x)(t) = \left\{ \begin{array}{ll} \phi(t); & t \in (-\infty, 0], \\ S_{\alpha,\beta}(t) [\phi(0) - g(0, \phi)] + g(t, x_t) \\ + \int_0^t P_\beta(t-s)f(s, x_s)ds \\ + \int_0^t P_\beta(t-s)\sigma(s, x_s)dS_Q^H(s), & \text{if } t \in (0, t_1], \\ h_k(t, x_t), & \text{if } t \in (t_k, s_{k+1}], \\ & k = 1, \dots, m, \\ S_{\alpha,\beta}(t - s_k)h_k(s_k, x_{s_k}) + g(s_k, x_{s_k}) \\ + \int_{s_k}^t P_\beta(t-s)f(s, x_s)ds & \text{if } t \in (s_k, t_{k+1}], \\ + \int_{s_k}^t P_\beta(t-s)\sigma(s, x_s)dS_Q^H(s), & k = 1, \dots, m. \end{array} \right.$$

For $\phi \in \mathcal{D}_{\mathcal{F}_0}$, we define $\tilde{\phi}$ by

$$\tilde{\phi}(t) = \left\{ \begin{array}{ll} \phi(t), & t \in (-\infty, 0], \\ S_{\alpha,\beta}(t) [\phi(0) - g(0, \phi)], & t \in (0, t_1]. \end{array} \right.$$

It is clear that $\tilde{\phi} \in \mathcal{D}_{\mathcal{F}_T}^\gamma$. Let $x(t) = z(t) + \tilde{\phi}(t)$; $t \in (-\infty, T]$, $z(t)$ satisfies that

$$z(t) = \left\{ \begin{array}{ll} 0, & \text{for } t \in (-\infty, 0], \\ g(t, z_t + \tilde{\phi}_t) + \int_0^t S_{\alpha,\beta}(t-s)f(s, z_s + \tilde{\phi}_s)ds \\ + \int_0^t P_\beta(t-s)\sigma(s, z_s + \tilde{\phi}_s)dS_Q^H(s), & \text{for } t \in (0, t_1], \\ h_k(t, z_t + \tilde{\phi}_t), & \text{for } t \in (t_k, s_k], \\ S_{\alpha,\beta}(t - s_k)h_k(s_k, z_{s_k} + \tilde{\phi}_{s_k}) + g(s_k, z_{s_k} + \tilde{\phi}_{s_k}) \\ + \int_{s_k}^t P_\beta(t-s)f(s, z_s + \tilde{\phi}_s)ds & \text{for } t \in (s_k, t_{k+1}], \\ + \int_{s_k}^t P_\beta(t-s)\sigma(s, z_s + \tilde{\phi}_s)dS_Q^H(s), & k = 1, \dots, m. \end{array} \right.$$

So, for any $z \in \mathcal{D}'_{\mathcal{F}_T}$, we have $\mathcal{D}'_{\mathcal{F}_T} = \{z \in \mathcal{D}_{\mathcal{F}_T}^\gamma, \text{ such that } z(0) = 0\}$, then $(\mathcal{D}'_{\mathcal{F}_T}, \|\cdot\|_{\mathcal{F}_T})$ is a Banach space.

Let the operator $\tilde{\Phi} : \mathcal{D}'_{\mathcal{F}_T} \rightarrow \mathcal{D}'_{\mathcal{F}_T}$ be defined by

$$\tilde{\Phi}(x)(t) = \left\{ \begin{array}{ll} 0, & \text{for } t \in (-\infty, 0], \\ \begin{aligned} &g(t, z_t + \tilde{\phi}_t) \\ &+ \int_0^t P_\beta(t-s)f(s, z_s + \tilde{\phi}_s)ds \\ &+ \int_0^t P_\beta(t-s)\sigma(s, z_s + \tilde{\phi}_s)dS_Q^H(s), \end{aligned} & \text{for } t \in (0, t_1], \\ \begin{aligned} &h_k(t, z_t + \tilde{\phi}_t), \\ &S_{\alpha, \beta}(t-s_k)h_k(s_k, z_{s_k} \\ &+ \tilde{\phi}_{s_k}) + g(s_k, z_{s_k} + \tilde{\phi}_{s_k}) \end{aligned} & \text{for } t \in (s_k, t_{k+1}], \\ \begin{aligned} &+ \int_{s_k}^t P_\beta(t-s)\sigma(s, z_s + \tilde{\phi}_s)dS_Q^H(s), \end{aligned} & k = 1, \dots, m. \end{array} \right.$$

From the assumptions, it is clear that $\tilde{\Phi}$ is well defined. Now we need only to show that $\tilde{\Phi}$ is a contraction mapping.

Case 1. For $u, v \in \mathcal{D}'_{\mathcal{F}_T}$, and for $t \in [0, t_1]$ we have

$$\begin{aligned} &\mathbb{E} \left\| t^{1-\gamma} \left[\tilde{\Phi}(u(t)) - \tilde{\Phi}(v(t)) \right] \right\|^2 \\ &\leq 3t^{2(1-\gamma)} \mathbb{E} \left\| g(t, u_t + \tilde{\phi}_t) - g(t, v_t + \tilde{\phi}_t) \right\|^2 \\ &\quad + 3t^{2(1-\gamma)} \mathbb{E} \left\| \int_0^t P_\beta(t-s) \left[f(s, u_s + \tilde{\phi}_s) - f(s, v_s + \tilde{\phi}_s) \right] \right\|^2 ds \\ &\quad + 3t^{2(1-\gamma)} \mathbb{E} \left\| \int_0^t P_\beta(t-s) \left[\sigma(s, u_s + \tilde{\phi}_s) - \sigma(s, v_s + \tilde{\phi}_s) \right] dS_I^H(s) \right\|^2 \\ &\leq I_1 + I_2 + I_3, \end{aligned} \tag{12}$$

where

$$\begin{aligned} I_1 &:= 3t^{2(1-\gamma)} \mathbb{E} \left\| g(t, u_t + \tilde{\phi}_t) - g(t, v_t + \tilde{\phi}_t) \right\|^2 \\ &\leq 3t^{2(1-\gamma)} K_g \left\| u - v \right\|_{\mathcal{D}'_{\mathcal{F}_T}}^2, \\ I_2 &:= 3t^{2(1-\gamma)} \mathbb{E} \left\| \int_0^t P_\beta(t-s) \left[f(s, u_s + \tilde{\phi}_s) - f(s, v_s + \tilde{\phi}_s) \right] \right\|^2 ds \\ &\leq 3 \frac{t^{2(1-\gamma)} M}{\Gamma^2(\beta)} \mathbb{E} \int_0^t (t-s)^{2(\beta-1)} \left\| f(s, u_s + \tilde{\phi}_s) - f(s, v_s + \tilde{\phi}_s) \right\|^2 ds \\ &\leq 3 \frac{t^{2\alpha(\beta-1)} L_f M}{(\Gamma(\beta))^2} \left\| u - v \right\|_{\mathcal{D}'_{\mathcal{F}_T}}^2, \end{aligned}$$

$$\begin{aligned}
I_3 &:= 3t^{2(1-\gamma)} \mathbb{E} \left\| \int_0^t P_\beta(t-s) \left[\sigma(s, u_s + \tilde{\phi}_s) - \sigma(s, v(s) + \tilde{\phi}_s) \right] dS_Q^H(s) \right\|^2 \\
&\leq 3t^{2(H-\gamma)+1} C_H \int_0^t \left\| P_\beta(t-s) \left[\sigma(s, u_s + \tilde{\phi}_s) - \sigma(s, v(s) + \tilde{\phi}_s) \right] \right\| ds \left\|_{L_Q^0}^2 \\
&\leq \frac{3t^{2(H-\gamma)+1} C_H M}{(\Gamma(\beta))^2} \int_0^t (t-s)^{2(\beta-1)} \left\| \sigma(s, u_s + \tilde{\phi}_s) - \sigma(s, v(s) + \tilde{\phi}_s) \right\|_{L_Q^0} \\
&\leq \frac{ML_\sigma t^{2(H-\alpha+\alpha\beta)}}{(\Gamma(\beta))^2} \|u - v\|_{\mathcal{D}'_{\mathcal{F}_T}}^2.
\end{aligned}$$

By taking the supremum over t , we obtain

$$\begin{aligned}
&\| \tilde{\Phi}(u)(t) - \tilde{\Phi}(v)(t) \|_{\mathcal{D}'_{\mathcal{F}_T}}^2 \\
&= \sup_{t \in [0, t_1]} \mathbb{E} \left\| t^{1-\gamma} \left[\tilde{\Phi}(u(t)) - \tilde{\Phi}(v(t)) \right] \right\|^2 \\
&\leq 3t_1^{2(\alpha\beta+1)} \left(t_1^{1-\alpha-\beta} K_g + \frac{t_1^{-\alpha} L_f M}{(\Gamma(\beta))^2} + \frac{ML_\sigma t_1^{H-\alpha}}{(\Gamma(\beta))^2} \right) \|u - v\|_{\mathcal{D}'_{\mathcal{F}_T}}^2.
\end{aligned}$$

Case 2. For $u, v \in \mathcal{D}'_{\mathcal{F}_T}$, $t \in (t_k, s_k]$, $k = 1, \dots, m$,

$$\begin{aligned}
\mathbb{E} \left\| t^{1-\gamma} \left[\tilde{\Phi}(u)(t) - \tilde{\Phi}(v)(t) \right] \right\|^2 &\leq L_{h_k} \|u - v\|_{\mathcal{D}'_{\mathcal{F}_T}}^2 \\
&\leq 2\tilde{K} t^{2(1-\gamma)} L_{h_k} \|u_t - v_t\|_{\mathcal{D}'_{\mathcal{F}_T}}^2.
\end{aligned}$$

By taking the supremum over t , we obtain

$$\begin{aligned}
\| \tilde{\Phi}(u)(t) - \tilde{\Phi}(v)(t) \|_{\mathcal{D}'_{\mathcal{F}_T}}^2 &= \sup_{t \in [t_k, s_k], k=1, \dots, m} \mathbb{E} \left\| t^{1-\gamma} \left[\tilde{\Phi}(u(t)) - \tilde{\Phi}(v(t)) \right] \right\|^2 \\
&\leq 2L_{h_k} T^{2(1-\gamma)} \|u - v\|_{\mathcal{D}'_{\mathcal{F}_T}}^2.
\end{aligned}$$

Case 3. For $u, v \in \mathcal{D}'_{\mathcal{F}_T}$ and for $t \in (s_k, t_{k+1}]$, $k = 1, \dots, m$, we have

$$\begin{aligned}
&\mathbb{E} \left\| t^{1-\gamma} \left(\tilde{\Phi}(u)(t) - \tilde{\Phi}(v)(t) \right) \right\|^2 \\
&\leq 4t^{2(1-\gamma)} \mathbb{E} \left\| S_{\alpha, \beta}(t - s_k) \left[h(s_k, u_{s_k} + \tilde{\phi}_{s_k}) - h(s_k, v_{s_k} + \tilde{\phi}_{s_k}) \right] \right\|^2 \\
&\quad + 4t^{2(1-\gamma)} \mathbb{E} \left\| \left(g(t, u_t + \tilde{\phi}_t) - g(t, v_t + \tilde{\phi}_t) \right) \right\|^2 \\
&\quad + 4t^{2(1-\gamma)} \mathbb{E} \left\| \int_{s_k}^{t_{k+1}} P_\beta(t-s) \left[f(s, u_s + \tilde{\phi}_s) - f(s, v_s + \tilde{\phi}_s) \right] \right\|^2 ds
\end{aligned}$$

$$\begin{aligned}
& + 4t^{2(1-\gamma)} \mathbb{E} \left\| \int_{s_k}^{t_{k+1}} P_\beta(t-s) \left[\sigma(s, u_s + \tilde{\phi}_s) - \sigma(s, v_s + \tilde{\phi}_s) \right] dS_Q^H(s) \right\|^2 \\
& \leq I_1 + I_2 + I_3 + I_4,
\end{aligned}$$

where

$$\begin{aligned}
I_1 & = 4t^{2(1-\gamma)} \mathbb{E} \left\| S_{\alpha, \beta}(t-s_k) \left[h(s_k, u_{s_k} + \tilde{\phi}_{s_k}) - h(s_k, v_{s_k} + \tilde{\phi}_{s_k}) \right] \right\|^2 \\
& \leq 4t^{2(1-\gamma)} \frac{Mt^{2(\alpha-1)(\beta-1)}}{\Gamma(\alpha(1-\alpha) + \beta)^2} \mathbb{E} \left\| h(s_k, u_{s_k} + \tilde{\phi}_{s_k}) - h(s_k, v_{s_k} + \tilde{\phi}_{s_k}) \right\|^2 \\
& \leq \frac{4MLh_k}{\Gamma(\alpha(1-\alpha) + \beta)^2} \|u-v\|_{\mathcal{D}'_{\mathcal{F}_T}}^2,
\end{aligned}$$

$$\begin{aligned}
I_2 & = 4t^{2(1-\gamma)} \mathbb{E} \left\| \left(g(t, u_t + \tilde{\phi}_t) - g(t, v_t + \tilde{\phi}_t) \right) \right\|^2 \\
& \leq 4t^{2(1-\gamma)} K_g \|u-v\|_{\mathcal{D}'_{\mathcal{F}_T}}^2,
\end{aligned}$$

$$\begin{aligned}
I_3 & = 4t^{2(1-\gamma)} \mathbb{E} \left\| \int_{s_k}^{t_{k+1}} P_\beta(t-s) \left[f(s, u_s + \tilde{\phi}_s) - f(s, v_s + \tilde{\phi}_s) \right] ds \right\|^2 \\
& \leq 4t^{2(1-\gamma)} \mathbb{E} \int_{s_k}^{t_{k+1}} \|P_\beta(t-s) \left[f(s, u_s + \tilde{\phi}_s) - f(s, v_s + \tilde{\phi}_s) \right]\|^2 ds \\
& \leq \frac{4t^{2(1-\gamma)} M(t_{k+1} - s_k)^{2(\beta-1)}}{(\Gamma(\beta))^2} \mathbb{E} \int_{s_k}^{t_{k+1}} \|f(s, u_s + \tilde{\phi}_s) - f(s, v_s + \tilde{\phi}_s)\|^2 ds \\
& \leq \frac{4t^{2(1-\gamma)} M(t_{k+1} - s_k)^{2(\beta-1)} L_f}{(\Gamma(\beta))^2} \|u-v\|_{\mathcal{D}'_{\mathcal{F}_T}}^2,
\end{aligned}$$

$$\begin{aligned}
I_4 & = 4t^{2(1-\gamma)} \mathbb{E} \left\| \int_{s_k}^{t_{k+1}} P_\beta(t-s) \left[\sigma(s, u_s + \tilde{\phi}_s) - \sigma(s, v_s + \tilde{\phi}_s) \right] dS_Q^H(s) \right\|^2 \\
& \leq 3t^{2(H-\gamma)+1} C_H \mathbb{E} \int_{s_k}^{t_{k+1}} \|P_\beta(t-s) \left[\sigma(s, u_s + \tilde{\phi}_s) - \sigma(s, v_s + \tilde{\phi}_s) \right]\|^2_{L_Q^0} ds \\
& \leq \frac{3t^{2(H-\gamma)+1} C_H M}{(\Gamma(\beta))^2} \mathbb{E} \int_{s_k}^{t_{k+1}} (t-s)^{2(\beta-1)} \|\sigma(s, u_s + \tilde{\phi}_s) - \sigma(s, v_s + \tilde{\phi}_s)\|^2_{L_Q^0} ds \\
& \leq \frac{C_H M L_\sigma t^{2(H-\gamma)+1} (t_{k+1} - s_k)^{2(\beta-1)}}{(\Gamma(\beta))^2} \|u-v\|_{\mathcal{D}'_{\mathcal{F}_T}}^2
\end{aligned}$$

By taking the supremum over t , we obtain

$$\begin{aligned} & \| \tilde{\Phi}(u)(t) - \tilde{\Phi}(v)(t) \|_{\mathcal{D}'_{\mathcal{F}_T}}^2 \\ & \leq \left(\frac{4MLh_k}{\Gamma(\alpha(1-\alpha) + \beta)^2} + 4t^{2(1-\gamma)}K_g + \frac{4t^{2(1-\gamma)}M(t_{k+1} - s_k)^{2(\beta-1)}L_f}{(\Gamma(\beta))^2} \right. \\ & \quad \left. + \frac{C_HML_\sigma t^{2(H-\gamma)+1}(t_{k+1} - s_k)^{2(\beta-1)}}{(\Gamma(\beta))^2} \right) \| u - v \|_{\mathcal{D}'_{\mathcal{F}_T}}^2, \end{aligned}$$

which implies that $\tilde{\Phi}$ is a contraction and there exists a unique fixed point $z(t) \in \mathcal{D}'_{\mathcal{F}_T}$ of $\tilde{\Phi}$, so $x_t \in \mathcal{D}'_{\mathcal{F}_T}$ is a mild solution of (1). The proof is completed. \square

4. Application

$$\left\{ \begin{aligned} & D_{0^+}^{\frac{1}{2}, \frac{1}{4}} [v_t(\cdot, \xi) - G(t, v_t(\cdot, \xi))] \\ & = \frac{\partial^2}{\partial \xi^2} [v_t(\cdot, \xi) - G(t, v_t(\cdot, \xi))] dt, \quad \text{for } 0 \leq \xi \leq \pi, t \in [s_k, t_{k+1}], \\ & + F(t, v_t(\cdot, \xi) + \sigma(t, v_t(\cdot, \xi)) \frac{dS_Q^H(t)}{dt}, \quad k = 0, \dots, m, \\ & v(t, \xi) = H_k(t, v_t(\cdot, \xi)), \quad \text{for } t \in (t_k, s_k], k = 1, 2, \dots, m, \\ & v_t(\cdot, 0) = v_t(\cdot, \pi) = 0, \quad \text{for } t \in [0, 2], \\ & (I_0^{\frac{3}{8}} v_t(\cdot, \xi))|_{t=0} = \phi(t, \xi), \quad \text{for } t \in (-\infty, 0], \end{aligned} \right. \tag{13}$$

where $D_{0^+}^{\frac{1}{2}, \frac{1}{4}}$ denotes the Hilfer fractional derivative. $S_Q^H(t)$ is an Q -sub-f.B.m with Hurst parameter $H \in (\frac{1}{2}, 1)$ defined on a complete probability space (Ω, \mathcal{F}, P) . The impulses times satisfy $0 = t_0 = s_0 < t_1 \leq s_1 < t_2 \leq \dots < t_m \leq s_m < t_{m+1} = T$, for $t > 0$. v_t means a segment solution which is defined by $v(\cdot, \cdot) : (-\infty, T] \times \Omega \rightarrow U$. Then for any $t \geq 0$, $v_t(\cdot, \cdot) : (-\infty, 0) \times \Omega \rightarrow U$ is given by $v_t(\theta, \omega) = x(t + \theta, \omega)$, for $\theta \in (-\infty, 0]$, $\omega \in \Omega$ with its value in $\mathcal{D}_{\mathcal{F}_T}^{\frac{5}{8}}$, and $U = L^2[0, \pi]$. $F, G : [0, 2] \times \mathcal{D}_{\mathcal{F}_T}^{\frac{5}{8}} \rightarrow \mathbb{R}$ are continuous functions. $I_0^{\frac{3}{8}}$ is the fractional integral of order $\frac{3}{8} = 1 - \frac{5}{8}$, where $\gamma = \frac{5}{8} = \frac{1}{2} + \frac{1}{4} - \frac{1}{8}$.

Now let

$y(t)(\xi) = u(t, \xi), t \in [0, 2], \xi \in [0, \pi],$
 $H_k(t, \phi(\theta, \xi)) = h_k(t, \phi)(\xi), \theta \in (-\infty, 0), \xi \in [0, \pi] k = 1, \dots, m,$ and,
 $\phi(\theta)(\xi) = \phi(\theta, \xi).$ We need now to define the operator $Q : K \rightarrow K,$ for this we choose a sequence $\{\sigma_n\}_{n \geq 1} \in \mathbb{R}^+$ such that $Qe_n = \sigma_n e_n$ and suppose that $tr(Q) = \sum_{n=1}^{\infty} \sqrt{\sigma_n} < \infty.$

The process $S_Q^H(s)$ will be defined by $S_Q^H(t) = \sum_{n=1}^{\infty} S_n^H(t) \sqrt{\sigma_n} e_n,$ where $H \in (\frac{1}{2}, 1)$ and $\{S_n^H(t)\}_{n \in \mathbb{N}}$ is a sequence of one dimensional standard sub-fractional Brownian motions mutually independent over $(\omega, \mathcal{F}, P).$

Finally we assume that:

- For all $k = 0, \dots, m,$ the function $f : [s_k, t_{k+1}] \times \mathcal{D}_{\mathcal{F}_T}^{\frac{5}{8}} \rightarrow U$ defined by $f(t, v)(\cdot) = F(t, v(\cdot))$ is continuous and we impose conditions on F to verify assumption $(H_3).$ For example we take $F(t, \phi) = t + \frac{2\phi}{1 + \|\phi\|_{\mathcal{D}^{\frac{5}{8}}}}; t \in [s_k, t_{k+1}]; \phi \in \mathcal{D}_{\mathcal{F}_T}^{\frac{5}{8}}.$
- For all $k = 0, \dots, m,$ the function $\sigma : [s_k, t_{k+1}] \times \mathcal{D}_{\mathcal{F}_T}^{\frac{5}{8}} \rightarrow L_Q^0(K, U)$ is continuous. We impose conditions on σ to make assumptions (H_5) hold. We put: $\sigma(t, \phi) = t^3 + \sin\phi; t \in [s_k, t_{k+1}]; \phi \in \mathcal{D}_{\mathcal{F}_T}^{\frac{5}{8}}.$
- For all $k = 0, \dots, m,$ the function $h_k : [t_k, s_k] \times \mathcal{D}_{\mathcal{F}_T}^{\frac{5}{8}} \rightarrow U$ defined by $h_k(t, v)(\cdot) = H_k(t, v(\cdot))$ is continuous and we impose conditions on H_k to make assumption (H_6) hold. For example we take: $H_k(t, \phi) = R_k \phi, \xi \in \Omega, t \in [s_k, t_{k+1}], \phi \in \mathcal{D}_{\mathcal{F}_T}^{\frac{5}{8}}.$

Thus the problem (13) can be written in the abstract form

$$\left\{ \begin{array}{l} D_{0+}^{\alpha, \beta} X(t, x_t) = A(t) X(t, x_t) \\ + f(t, x_t) + \sigma(t, x_t) \frac{dS_Q^H(t)}{dt}, \quad \text{for } t \in [s_k, t_{k+1}], k = 0, \dots, m, \\ x(t) = h_k(t, x_t), \quad \text{for } t \in (t_k, s_k], k = 1, 2, \dots, m, \\ (I_0^{1-\gamma} x)(t)|_{t=0} = \phi \in \mathcal{D}_{\mathcal{F}_0}((-\infty, 0], U). \end{array} \right. \tag{14}$$

Thanks to these assumptions, it is easy to check that $(H1)-(H6)$ hold and thus assumptions in Theorem 3.1 are fulfilled, ensuring that system 13 possesses a mild solution on $(-\infty, T).$

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