

ON COMPACT PERTURBATIONS OF m -ACCRETIVE AND MAXIMAL MONOTONE OPERATORS IN BANACH SPACES

BY

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Abstract. Let X be a real Banach space and G a bounded, open subset of X . The solvability of the problem $Tx + Cx \ni s$, $s \in X$ in $D(T) \cap \bar{G}$ is considered, where $T : X \supset D(T) \rightarrow 2^X$ is m -accretive and $C : D(T) \rightarrow X$ is either compact or is continuous with $(T + I)^{-1}$ being compact, under the various assumptions of boundary conditions and coercivities which the operators T and C possess. Certain eigenvalue results are given involving the solvability of $Tx + \lambda Cx \ni 0$ with respect to $(\lambda, x) \in (0, \infty) \times \partial G$. Some analogous result on maximal monotone operators are also discussed in this paper.

1. Introduction preliminaries. In this paper, the symbol X stands for a real Banach space with norm $\|\cdot\|$ and (normalized) duality mapping F . For $x \in X$ and $x^* \in X^*$, we use the symbol $\langle x, x^* \rangle$ or the symbol $\langle x^*, x \rangle$ to denote the value of x^* at x . An operator $T : X \supset D(T) \rightarrow 2^X$ is called "accretive" if for every $x, y \in D(T)$, $u \in Tx$ and $v \in Ty$, there exists $j \in F(x - y)$ such that

$$\langle u - v, j \rangle \geq 0$$

An accretive operator T is m -accretive if $R(T + \lambda I) = X$ for all $\lambda \in (0, \infty)$. An accretive operator T is called "strongly accretive" if there exists a con-

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stant $\alpha > 0$ such that : for each $x, y \in D(T)$ there exists $j \in F(x - y)$ satisfying

$$(*) \quad \langle u - v, j \rangle \geq \alpha \|x - y\|^2$$

for all $u \in Tx, v \in Ty$. It is called strongly accretive at zero if $0 \in D(T)$ and (*) holds for all $u \in Tx, y = 0$ and $v \in T(0)$. Let a function $\phi : R_+ \rightarrow R_+$ be strictly increasing with $\phi(0) = 0$, where $R_+ = [0, \infty)$. It is called ϕ -accretive if

$$\langle u - v, j \rangle \geq \phi(\|x - y\|)\|x - y\|,$$

for all $x, y \in D(T)$, $u \in Tx$ and $v \in Ty$. It is called ϕ -expansive on $D(T)$, if $\|u - v\| \geq \phi(\|x - y\|)$ for all $x, y \in D(T)$, $u \in Tx$ and $v \in Ty$.

We denote by $B_r(0)$ the open ball with center at zero and radius $r > 0$. For an m -accretive operator T , $\lambda \in (0, \infty)$ the "resolvent" $J_\lambda : X \rightarrow D(T)$ of T are defined by $J_\lambda = (I + \frac{1}{\lambda}T)^{-1}$ and the "Yosida approximation" $T_\lambda : X \rightarrow X$ of T is defined by $T_\lambda = \lambda(I - J_\lambda)$. For $x \in X$, we define $|Tx|$ by

$$|Tx| = \lim_{\lambda \rightarrow 0} \|T_\lambda x\|.$$

if the limit exists. For a set Q , we set $|Q| = \inf\{\|y\|; y \in Q\}$.

Some well-known properties of J_λ and T_λ are given below:

1. $\|J_\lambda x - J_\lambda y\| \leq \|x - y\|$ for all $x, y \in X$.
2. $\|J_\lambda x - x\| = \frac{1}{\lambda} \|T_\lambda x\| \leq \frac{1}{\lambda} \inf\{\|y\|; y \in Tx\} = \frac{1}{\lambda} |Tx|$ for all $x \in D(T)$.
3. T_λ is m -accretive on X and $\|T_\lambda x - T_\lambda y\| \leq 2\lambda \|x - y\|$ for all $\lambda > 0$, $x, y \in X$.
4. $T_\lambda x \in TJ_\lambda x$ for all $x \in X$.

For these facts and other general results involving accretive operators, the reader may refer to Barbu [1], Browder [4], Cioranescu [5], Deimling [6], Lakshmikantham and Leela [26] and Pavel [31]. We cite the books of Lloyd [27], Rothe [33] and the paper of Nagumo [29] as references to the degree theory discussed herein. For a survey article on recent mapping theorems

involving compactness and accretivity, we refer to [22]. We denote by Γ the family of all functions $\beta : R^+ \rightarrow R^+$ such that $\beta(r) \rightarrow 0$ as $r \rightarrow \infty$.

In the sequel, "continuous" means "strongly continuous" and the symbol " \rightarrow " (" \xrightarrow{w} ") means strong (weak) convergence. The symbol ∂G , $\text{int } G$, \bar{G} denote the boundary, interior and closure of the set G , respectively.

An operator $T : X \supset D(T) \rightarrow Y$, Y is a Banach space, is bounded if it maps bounded subsets of $D(T)$ onto bounded set of Y . It is compact if it is continuous and maps bounded subsets of $D(T)$ onto relatively compact sets of Y . It is called demicontinuous (completely continuous) if it is strong-weak (weak-strong) continuous on $D(T)$ into Y .

2. Perturbations of M -accretive operators. Kartsatos introduced in [19, Theorem 7] a homotopy argument concerning the sum of two operators $T+C$, where T is demicontinuous, strongly accretive and C is compact. The space X^* is assumed to be uniformly convex. He showed in [19] that the equation $Tx + Cx \ni s$ can be solved under some boundary conditions on an open, bounded subset G of X . This result is based on Kartsatos' invariance of domain result for demicontinuous, ϕ -accretive or strongly accretive mappings in [18, Theorem 1]. Many authors have established new results related the involving equations $Tx + Cx \ni s$ and their applications, see [8, 12-13, 16-17, 19-25, 28, 35].

Our purpose here is to consider sums of three operators $T+A+C$, where T is m -accretive, A is demicontinuous, bounded and strongly accretive, and C is compact. Results for such triplets of operators can be proved by using simple the homotopy theory for Leray-Schauder operators in connection with the methods and the results that have been developed in [8]-[25].

Theorem 1. *Let X^* be uniformly convex and $0 \in G$ be a bounded, open subset of X . Let $T : X \supset D(T) \rightarrow 2^X$ be m -accretive with $0 \in D(T)$, $A : \bar{G} \subset D(T) \rightarrow X$ bounded, demicontinuous and strongly accretive and $C : \bar{G} \rightarrow X$ compact. Assume that $Q \subset X$ and for every $q \in Q$ such that*

$$(1) \quad \langle Ax + Cx - q, Fx \rangle \geq 0, \quad x \in D(T) \cap \partial G.$$

Then $Q \subset (T + A + C)(D(T) \cap \bar{G})$.

Proof. For fixed $q \in Q$, we want to solve the problem

$$Tx + Ax + Cx \ni q.$$

First, for any positive integer n , we consider the problem

$$T_n x + Ax + Cx = q.$$

We may assume that $0 \in T(0)$, $A(0) = 0$, for otherwise, we may consider the operators $\check{T}x \equiv Tx - v$, $\check{A}x \equiv Ax - u$, $\check{C}x \equiv Cx + v + u$, instead of the operators T, A, C , where v is some point in $T(0)$ and $A(0) = u$. It is clear that these mappings have exactly the same properties as T, A, C , respectively. We now note that the operator $\check{T} : x \rightarrow T_n x + Ax$ is demicontinuous and strongly accretive on \bar{U} , where $U \equiv D(T) \cap G$, because the Yosida approximation T_n is a Lipschitz continuous m -accretive mapping defined on all of X . Due to Theorem 1 in [18], we know that $\check{T}U$ is open and $\check{T}\bar{U}$ is closed. Moreover, \check{T}^{-1} exists and is continuous and bounded on the set $\check{T}\bar{U} \subset \check{T}\bar{U}$. Also $\partial\check{T}U \subset \check{T}(\partial U)$ and

$$\check{T}^{-1}(\partial\check{T}U) \subset \partial\check{T}^{-1}(\check{T}U) = \partial U.$$

These facts can be found in the proof of Theorem 7 [19].

It follows that the Leray-Schauder degree $d(H(t, \cdot), \check{T}U, 0)$ is well-defined for the mapping

$$H(t, y) = y + t(C\check{T}^{-1}y - q), \quad y \in \overline{\check{T}(U)}, \quad t \in [0, 1].$$

We also note that $H(0, \partial\check{T}U) = y \in \check{T}(U)$ and $0 \in \check{T}(U)$ because $\check{T}(0) = 0$. In order to show that $H(1, y) = 0$ is solvable in $\overline{\check{T}(U)}$, we must show that the equation $H(t, y) = 0$ has no solution on $\partial\check{T}(U)$ for any $t \in [0, 1)$. Obviously, this is trivial for $t = 0$. Assume that there exist $t \in (0, 1)$ and $y_t \in \partial\check{T}(U)$ such that $H(t, y_t) = 0$. Then, let $x_t = \check{T}^{-1}y_t \in \partial U$, we obtain

$$T_n x_t + Ax_t + tCx_t = tq.$$

Since $T_n(0) = 0$, we obtain that

$$\langle T_n x_t, Fx_t \rangle \geq 0, \quad x_t \in \partial U.$$

Using this fact, we have

$$\begin{aligned} 0 &= \langle T_n x_t + Ax_t + t(Cx_t - q), Fx_t \rangle \\ &\geq \langle Ax_t + t(Cx_t - q), Fx_t \rangle > 0. \end{aligned}$$

We now prove the last inequality above, that is, we show that

$$(2) \quad \langle Ax_t + t(Cx_t - q), Fx_t \rangle > 0.$$

To this end, we observe that

$$\langle Ax_t, Fx_t \rangle \geq \alpha \|x_t\|^2 > 0.$$

where $\alpha > 0$ is the strong accretiveness constant of the operator A . This implies that (2) will be true if

$$\langle Cx_t - q, Fx_t \rangle \geq 0.$$

Assume that

$$\langle Cx_t - q, Fx_t \rangle < 0.$$

Then

$$\langle Ax_t, Fx_t \rangle \leq -t \langle Cx_t - q, Fx_t \rangle < -\langle Cx_t - q, Fx_t \rangle,$$

which is equivalent to

$$\langle Ax_t + Cx_t - q, Fx_t \rangle < 0.$$

Since $x_t \in D(T) \cap \partial G$, we have a contradiction to the assumption (1).

Consequently, (2) is true and implies that

$$\begin{aligned} 0 &= \langle T_n x_t + Ax_t + t(Cx_t - q), Fx_t \rangle \\ &\geq \langle Ax_t + t(Cx_t - q), Fx_t \rangle > 0. \end{aligned}$$

This contradiction implies that the equation $H(t, y) = 0$ has no solution on $\partial\tilde{T}(U)$ for any $t \in [0, 1)$, and hence the equation $T_n x + Ax + Cx = q$ is solvable with a solution $x_n \in \bar{U}$. Due to the boundedness of the operators A and C , we have that the sequence $\{T_n x_n\}$ is bounded and that $\{Cx_n\}$ is a precompact set. Then we have

$$\begin{aligned} & \alpha \|x_n - x_m\|^2 \\ & \leq \langle Ax_n - Ax_m, F(x_n - x_m) \rangle \\ & = - \langle T_n x_n - T_m x_m + Cx_n - Cx_m, F(x_n - x_m) \rangle \\ & \leq - \langle T_n x_n - T_m x_m, F(J_n x_n - J_m x_m) \rangle - \langle T_n x_n - T_m x_m, F(x_n - x_m) \\ & \quad - F(J_n x_n - J_m x_m) \rangle + \|Cx_n - Cx_m\| \cdot \|x_n - x_m\|. \\ & \leq \|T_n x_n - T_m x_m\| \cdot \|F(x_n - x_m) - F(J_n x_n - J_m x_m)\| \\ & \quad + \|Cx_n - Cx_m\| \cdot \|x_n - x_m\|. \end{aligned}$$

At this point, we note that $\|J_n x_n - x_n\| \leq \frac{1}{n} \|T_n x_n\|$, $\|Cx_n - Cx_m\| \rightarrow 0$ as $m, n \rightarrow \infty$, and F is locally uniformly continuous. Thus, $\{x_{n_k}\}$ is a Cauchy subsequence and $x_{n_k} \rightarrow x_0 \in \bar{U}$ as $k \rightarrow \infty$.

By the fact $\|J_{n_k} x_{n_k} - x_0\| \leq \|J_{n_k} x_{n_k} - x_{n_k}\| + \|x_{n_k} - x_0\| \rightarrow 0$ as $k \rightarrow \infty$, we have $J_{n_k} x_{n_k} \rightarrow x_0$. Since A is demicontinuous, $Ax_{n_k} \xrightarrow{w} Ax_0$, C is continuous, $Cx_{n_k} \rightarrow Cx_0$, hence $v_{n_k} \xrightarrow{w} -Ax_0 - Cx_0 + q$, where $v_n = -Ax_n - Cx_n + q \in Tx_n$. By the demiclosedness of T , we have that $x_0 \in D(T) \cap \bar{G}$ and $Tx_0 + Ax_0 + Cx_0 \ni q$ or $Q \subset (T + A + C)(D(T) \cap \bar{G})$.

As a special case of Theorem 1, we have the following result which is due to A. G. Kartsatos and X. Liu [24, Theorem 8].

Corollary 1. *Let X^* be uniformly convex. Let $T : X \supset D(T) \rightarrow 2^X$ be m -accretive with $0 \in D(T)$, $A : \overline{B_b(0)} \subset D(T) \rightarrow X$ bounded, demicontinuous and strongly accretive, and $C : \overline{B_b(0)} \rightarrow X$ compact. Assume that there exist $v \in T(0)$ and $r > 0$ such that*

$$\langle Ax + Cx, Fx \rangle \geq (r + \|v\|)b, \quad x \in \partial B_b(0).$$

Then $\overline{B_r(0)} \subset (T + A + C)(D(T) \cap \overline{B_b(0)})$.

Proof. We may set $Q = \overline{B_r(0)}$, then for every $q \in \overline{B_r(0)}$ we have

$$\begin{aligned} \langle Ax + Cx - q, Fx \rangle &\geq (r + \|v\|)b - \langle q, Fx \rangle \\ &\geq (r + \|v\|)b - r \cdot b \\ &= \|v\| \cdot b > 0, \end{aligned}$$

and Theorem 1 is applicable.

We want to study the applicability of Schauder's fixed point theorem to the problem considered herein. Kartsatos gave in [16, Lemma 1] a result in this direction to which the problem $Tx + Cx + \frac{1}{n}x = f$ is solvable for every $f \in X$, $n = 1, 2, \dots$, provided that T is single-valued m -accretive operator with $0 \in D(T)$ and $T(0) = 0$, and $C : X \rightarrow X$ is compact such that

$$\liminf_{m \rightarrow \infty} \left\{ (1/m) \sup_{\|x\| \leq m} (\|Cx\|) \right\} = 0.$$

We show below that we can extend the conclusion of this result to multi-valued operator T and obtain the sum of the operators $T + C$ is dense and surjective on X .

Theorem 2. *Let $T : X \supset D(T) \rightarrow 2^X$ be m -accretive and $C : D(T) \rightarrow X$ continuous with $(T + I)^{-1}$ being compact. Assume that*

$$(3) \quad \limsup_{m \rightarrow \infty, \|x\| \leq m} \left\{ (1/m) \|Cx\| \right\} = 0.$$

Then, for each $s \in X$, the equation

$$(4) \quad Tx + Cx + \frac{1}{n}x \ni s,$$

has a solution x_n for each $n \in N$. Assume further that

$$\liminf_{\|x\| \rightarrow \infty, x \in D(T)} \frac{|Tx + Cx|}{\|x\|} > 0.$$

Then $\overline{R(T + C)} = X$. Furthermore, if one of the following conditions holds:

(a) X is uniformly convex and $C : \overline{D(T)} \rightarrow X$ is completely continuous,

(b) C is bounded,

then $R(T + C) = X$.

Proof. We may assume that $0 \in D(T)$ and $0 \in T(0)$. Otherwise, for $z \in D(T)$, $v \in Tz$, we may consider the operators $\tilde{T}(x) \equiv T(x+z) - v$, $\tilde{C}(x) \equiv C(x+z) + v$, for every $x \in D(T) - z$. It is easy to see that the operator \tilde{T} is m -accretive on $D(\tilde{T}) \equiv D(T) - z$. To show the compactness of the operator $(\tilde{T} + I)^{-1}$ and hence $(\tilde{T} + \lambda I)^{-1}$, for every $\lambda > 0$. We note that the m -accretivity of the operator \tilde{T} , implies the continuity of $(\tilde{T} + I)^{-1}$. Let $\{y_n\}$ be a bounded sequence in X and let $x_n = (\tilde{T} + I)^{-1}y_n$. Then

$$y_n = \tilde{v}_n + x_n = v_n + x_n - v,$$

where $\tilde{v}_n \in \tilde{T}x_n$ and $v_n \in T(x_n + z)$. Thus,

$$(x_n + z) + v_n = y_n + z + v,$$

or

$$x_n = (T + I)^{-1}(y_n + z + v) - z.$$

By the boundedness of $\{y_n\}$, z and v , as well as the compactness of the operator $(T + I)^{-1}$, we concluded that $\{x_n\}$ lies in a compact set. This proves the compactness of the operator $(\tilde{T} + I)^{-1}$. To see that (3) is satisfied for the operator \tilde{C} , we observe that

$$\begin{aligned} & m^{-1} \left(\sup_{\|x\| \leq m} \{\|\tilde{C}x\|\} \right) \\ &= m^{-1} \left(\sup_{\|x\| \leq m} \{\|C(x+z) + v\|\} \right) \\ &\leq m^{-1} \left(\sup_{\|x\| \leq m} \{\|C(x+z)\|\} + \|v\| \right) \\ &= m^{-1} \left(\sup_{\|y-z\| \leq m} \{\|Cy\|\} + \|v\| \right) \\ &\leq m^{-1} \left(\sup_{\|y\| \leq m+\|z\|} \{\|Cy\|\} \right) + m^{-1}\|v\| \\ &= m^{-1}(m + \|z\|) \cdot \left(\frac{1}{m + \|z\|} \right) \left(\sup_{\|y\| \leq m+\|z\|} \{\|Cy\|\} \right) + m^{-1}\|v\| \\ &\rightarrow 0 \text{ as } m \rightarrow \infty. \end{aligned}$$

we have shown that it suffices to prove the theorem with $0 \in D(T)$ and $0 \in T(0)$.

Now, we fix n , and consider the equation

$$u = \left(T + \frac{1}{n}I\right)^{-1} (s - Cu), \quad u \in X.$$

Now, let $u \in D(T)$ be given. Then for $j \in F(u)$, we have

$$(5) \quad \left\langle v + \frac{1}{n}u, j \right\rangle = \langle v, j \rangle + \frac{1}{n}\|u\|^2 \geq \frac{1}{n}\|u\|^2,$$

where $v \in Tu$. In order to solve (4), we apply the Schauder theorem to the compact operator $U : X \rightarrow X$ defined by

$$Uu = \left(T + \frac{1}{n}I\right)^{-1} (s - Cu), \quad u \in X.$$

Now we claim that U maps some closed ball of X into itself, suppose that this is not true. Then for each $m \in N$, there exists u_m such that $u_m \in \overline{B_m(0)}$ and $\|Uu_m\| > m$. It follows from (5) that we have

$$\begin{aligned} m < \|Uu_m\| &= \left\| \left(T + \frac{1}{n}I\right)^{-1} (s - Cu_m) \right\| \\ &\leq n(\|s\| + \|Cu_m\|) \end{aligned}$$

and by (3)

$$1 < n \left[\frac{1}{m}\|s\| + \frac{1}{m}\|Cu_m\| \right] \rightarrow 0 \quad \text{as } m \rightarrow \infty.$$

This is a contradiction. Consequently, there is a $r > 0$ such that $U(\overline{B_r(0)}) \subset \overline{B_r(0)}$. The Schauder theorem implies the solvability of the equation $Ux = x$, i.e., the solvability of the inclusion (4).

Let x_n be a solution of the equation (4). We claim that $\{x_n\}$ is a bounded sequence. To see this, assume that $\|x_n\| \rightarrow \infty$ as $n \rightarrow \infty$. Then, by our hypothesis, there exists a positive number p such that

$$\liminf_{n \rightarrow \infty} \frac{|Tx_n + Cx_n|}{\|x_n\|} \geq \liminf_{\|x\| \rightarrow \infty, x \in D(T)} \frac{|Tx + Cx|}{\|x\|} \geq p > 0.$$

However, we know that for some $v_n \in Tx_n$, we have

$$\|v_n + Cx_n\| = \left\| s - \frac{1}{n}x_n \right\| \leq \frac{1}{n}\|x_n\| + \|s\|$$

which implies

$$p \leq \liminf_{n \rightarrow \infty} \frac{\|v_n + Cx_n\|}{\|x_n\|} \leq \liminf_{n \rightarrow \infty} \left[\frac{1}{n} + \frac{\|s\|}{\|x_n\|} \right] = 0.$$

This contradiction says that $\{x_n\}$ is bounded, and hence $\frac{1}{n}x_n \rightarrow 0$ as $n \rightarrow \infty$. So we have $s \in \overline{R(T + C)}$.

Now, if (a) holds, then C is completely continuous and X is uniformly convex. Since $\{x_n\}$ is a bounded sequence, we may assume that $x_n \xrightarrow{w} x_0$ for some $x_0 \in \overline{D(T)}$ and that $Cx_n \rightarrow Cx_0$ implies $v_n \in Tx_n, v_n = -Cx_n - \frac{1}{n}x_n + s \rightarrow -Cx_0 + s$ as $n \rightarrow \infty$. By the fact that every m -accretive operator on uniformly convex space is demiclosed, so we have $x_0 \in D(T)$ and $Tx_0 + Cx_0 \ni s$.

In case (b), C is bounded. Since $\{x_n\}$ is a bounded sequence and satisfies that $v_n + Cx_n + \frac{1}{n}x_n = s$, for some $v_n \in Tx_n$. We may have

$$x_n = (T + I)^{-1} \left[s - Cx_n + \left(1 - \frac{1}{n}\right)x_n \right].$$

By the boundedness of the sequence $\{x_n\}$ and the operator C , as well as the compactness of $(T + I)^{-1}$ implies that $\{x_n\}$ lies in a compact set. Thus, it has a convergent subsequence $\{x_{n_k}\}$, say $x_{n_k} \rightarrow x_0 \in \overline{D(T)}$. The continuity of C implies $v_{n_k} = -Cx_{n_k} - \frac{1}{n_k}x_{n_k} + s \rightarrow -Cx_0 + s$ as $k \rightarrow \infty$, and the closedness of T implies that $x_0 \in D(T)$ and $Tx_0 + Cx_0 \ni s$.

The following result provides a "product condition" on CJ_1x for the solvability of $Tx + Cx \ni s$. He [15] studied a variant of equation, for single-valued operator T , by

$$(6) \quad TJ_1x + CJ_1x + \frac{1}{n}x = s.$$

This equation is equivalently to the equation $x - Sx = 0$, where

$$(7) \quad Sx = \frac{n}{1+n}(I - C)J_1x + \frac{n}{1+n}s.$$

If J_1 is a compact operator, then the operator S is also compact and (6) can be solved by using homotopy argument associated with the equation $x - Sx = 0$.

We are going to use equation (7) in order to get a new result for the range of $T + C$.

Theorem 3. *Let $T : X \supset D(T) \rightarrow 2^X$ be m -accretive with $0 \in D(T)$, $0 \in T(0)$ and $(T + I)^{-1}$ compact. Let $C : D(T) \rightarrow X$ be continuous. Let $s \in X$ and assume that there exist $K(s) > 0$ and $\beta = \beta_s \in \Gamma$ such that*

$$\langle CJ_1x - s, j \rangle \geq -K(s) - \beta(\|x\|)\|x\|,$$

for all $x \in X$ with $\|x\|$ sufficiently large and some $j \in F(x)$. Then $s \in \overline{R(T + C)}$.

Proof. We consider the approximating equation

$$TJ_1x + CJ_1x + \frac{1}{n}x = s, \quad n = 1, 2, \dots,$$

where s is a given point in X and $J_1 = (T + I)^{-1}$, which is equivalent to the equation

$$(8) \quad x = \frac{n}{1+n}(I - C)J_1x + \frac{n}{1+n}s.$$

Define the homotopy mapping $H(t, x)$ as follows: For $x \in X$,

$$H(t, x) = t \left[\frac{n}{1+n}(I - C)J_1x + \frac{n}{1+n}s \right], \quad t \in (0, 1],$$

and $H(0, x) = 0$. Since J_1 is a compact operator, C is a continuous operator, therefore for each $t \in (0, 1]$, the mapping $H(t, x)$ is compact on $x \in X$. It follows that the Leray-Schauder degree $d(I + H(t, \cdot), Q, 0)$ is well-defined for any ball $Q \equiv B_r(0)$ for some $r > 0$, provided that the equation $x - H(t, x) = 0$ has no solution on $\partial B_r(0)$ for all $t \in [0, 1]$.

In order to show that there is some $r > 0$ satisfying

$$\begin{aligned} d(I - H(t, \cdot), Q, 0) &= d(I - H(1, \cdot), Q, 0) \\ &= d(I - H(0, \cdot), Q, 0) \\ &= 1, \end{aligned}$$

for all $t \in [0, 1]$, we must show that all possible solutions x of the equations $x - H(t, x) = 0$ are uniformly bounded, i.e., they all lie in a ball $Q \equiv B_r(0)$ for some $r > 0$. If this is not true, there exist $\{t_m\} \subset (0, 1]$ and $\{x_m\} \subset X$ such that

$$x_m = \frac{n \cdot t_m}{1+n} (I - C)J_1 x_m + \frac{n \cdot t_m}{1+n} s$$

and $\|x_m\| \rightarrow \infty$. Since $J_1 x_m \in D(T)$, $0 \in D(T)$ and $0 \in T(0)$ we have $\|J_1 x_m\| \leq \|x_m\|$. Hence for some $j \in F(x_m)$ we have

$$\begin{aligned} \|x_m\|^2 &= \langle x_m, j \rangle \leq \frac{n \cdot t_m}{1+n} \|x_m\|^2 - \frac{n \cdot t_m}{1+n} \langle C J_1 x_m - s, j \rangle \\ &\leq \frac{n}{1+n} \|x_m\|^2 + \frac{n}{1+n} [K(s) + \beta(\|x_m\|)\|x_m\|] \end{aligned}$$

and thus

$$\frac{1}{n} \|x_m\|^2 \leq K(s) + \beta(\|x_m\|)\|x_m\|.$$

This shows the boundedness of the sequence $\{x_m\}$ and implies the solvability of eq. (8). Let u_n be a solution of eq. (8) for each $n \in N$. Then for some $j \in F(u_n)$, we have

$$\begin{aligned} \|u_n\|^2 &= \frac{n}{1+n} \langle J_1 u_n, j \rangle - \frac{n}{1+n} \langle C J_1 u_n - s, j \rangle \\ &\leq \frac{n}{1+n} \|u_n\|^2 + \frac{n}{1+n} [K(s) + \beta(\|u_n\|)\|u_n\|]. \end{aligned}$$

This implies that

$$\frac{1}{n} \|u_n\|^2 \leq K(s) + \beta(\|u_n\|)\|u_n\|.$$

for all large n . We conclude that $\frac{1}{n} \|u_n\| \rightarrow 0$ as $n \rightarrow \infty$ in all possible cases. Thus, we have $TJ_1 u_n + CJ_1 u_n \rightarrow s$, as $n \rightarrow \infty$. Consequently, $s \in \overline{R(T + C)}$.

In order to prove our next theorem, we need the following theorem which can be found in Guan and Kartsatos [14].

Theorem A. *Let $G \subset X$ be open, bounded with $0 \in G$. Let $C : \bar{G} \rightarrow X$ be compact and such that $\|Cx\| \geq \alpha$, $x \in \partial G$, where α is a positive constant number. Then there exists $\lambda_0 > 0$ and $x \in \partial G$ such that $(I - \lambda_0 C)x = 0$.*

The next result provides a method for proving the existence of certain eigenvalues for the pair (T, C) . A real number λ is called an eigenvalue of a pair of operators (T, C) if the equation $\lambda Tx + Cx \ni 0$ is solvable in $D(T) \cap D(C)$. The following theorem generalizes some results in Guan and Kartsatos [14]. The operator T does not have to be ϕ -expansive on ∂G . We also assume the boundedness of the operator T only on the set ∂G , for the approximate solvability of the relevant eigenvalue problems.

Theorem 4. *Let G be an open, bounded subset of X with $0 \in G$. Let $T : \bar{G} \rightarrow 2^X$ be accretive with $0 \in T(0)$, $0 \notin T(\partial G)$ and $T(\partial G)$ bounded. Let $C : \bar{G} \rightarrow X$ be continuous with $C(T + I)^{-1}$ being compact. Let the constant $\alpha > 0$ be such that $\|Cx\| \geq \alpha$, for all $x \in \partial G$, and satisfy one of the following conditions:*

- (i) X^* is uniformly convex and T is demicontinuous,
- (ii) T is continuous.

Then there exist $\lambda_0 > 0$ and $x_0 \in \partial G$ such that $\lambda_0 Cx_0 \in Tx_0$.

Proof. We consider the inclusion problem

$$(9) \quad Tx - \lambda Cx + \frac{1}{n}x \ni 0, \quad n = 1, 2, \dots,$$

or equivalently

$$(10) \quad u - \lambda C(T + \frac{1}{n}I)^{-1}u = 0$$

for all $n \in N$. We want to show that (9) has at least one solution, say, $(\lambda_n, x_n) \in (0, \infty) \times \partial G$. Then we shall show that $Tx - \lambda Cx \ni 0$ is solvable, with solution $(\lambda_0, x_0) \in (0, \infty) \times \partial G$. If $(\lambda, u) \in (0, \infty) \times \partial(\tilde{T}G)$ is a solution of (10), then $(\lambda, x) \in (0, \infty) \times \partial G$ is a solution of (9), where $\tilde{T} \equiv T + \frac{1}{n}I$ and $x = (T + \frac{1}{n}I)^{-1}u$. In fact, \tilde{T} is a strongly accretive and injective mapping such that $\tilde{T}G$ is open and $\tilde{T}\bar{G}$ is closed under the assumption (i)

[18, Theorem 1] or the assumption (ii) [7, Theorem 3]. Hence, under either one of these assumptions we have

$$\tilde{T}G \cup \partial(\tilde{T}G) = \overline{\tilde{T}G} \subset \overline{\tilde{T}\bar{G}} = \tilde{T}\bar{G} = \tilde{T}G \cup \tilde{T}(\partial G),$$

which implies that $\partial(\tilde{T}G) \subset \tilde{T}(\partial G)$. Consequently, the mapping $y \rightarrow y - \lambda C\tilde{T}^{-1}y$ is well-defined on $\overline{\tilde{T}G}$, and the range of the mapping $y \rightarrow \lambda C\tilde{T}^{-1}y$ on $\overline{\tilde{T}G}$ is a relatively compact subset of X . We also observe that if $u \in \partial(\tilde{T}G)$ then $\tilde{T}^{-1}u \in \tilde{T}^{-1}(\partial\tilde{T}G) \subset \partial G$ and $\|C\tilde{T}^{-1}u\| \geq \alpha$. Applying Theorem A, we obtain, for each n , a solution $(\lambda_n, u_n) \in (0, \infty) \times \partial(\tilde{T}G)$ of eq. (10). Letting $x_n = \tilde{T}^{-1}u_n$, we have the solvability of (9) with solution $(\lambda_n, x_n) \in (0, \infty) \times \partial G$, or

$$Tx_n - \lambda_n Cx_n + \frac{1}{n}x_n \ni 0, \quad n = 1, 2, \dots$$

Since $x_n = \tilde{T}^{-1}u_n$, we have that

$$(11) \quad u_n = v_n + \frac{1}{n}x_n$$

for some $v_n \in Tx_n$. Due to the boundedness of $\{v_n\}$, $\{x_n\}$, we have that $\{u_n\}$ is bounded. From the fact that $\{u_n\}$ is bounded and $\|C(T + \frac{1}{n}I)^{-1}u_n\| \geq \alpha$, it follows that $\{\lambda_n\}$ is also bounded. Thus, we may assume that $\lambda_{n_k} \rightarrow \lambda_0$ as $n_k \rightarrow \infty$. From (11), we have

$$v_n + x_n = u_n + \left(1 - \frac{1}{n}\right)x_n,$$

that is

$$x_n = (T + I)^{-1} \left[u_n + \left(1 - \frac{1}{n}\right)x_n \right],$$

which implies that

$$C(T + \frac{1}{n}I)^{-1}u_n = Cx_n = C(T + I)^{-1} \left[u_n + \left(1 - \frac{1}{n}\right)x_n \right].$$

The fact $C(T + I)^{-1}$ is compact and $\{u_n\}$, $\{x_n\}$ are bounded imply that $\{Cx_n\}$ lies in a compact set, we may assume that $Cx_{n_k} \rightarrow y \in X$. Hence we obtain that

$$v_{n_k} + \frac{1}{n_k} x_{n_k} = \lambda_{n_k} C x_{n_k} \rightarrow \lambda_0 y$$

for some $v_{n_k} \in T x_{n_k}$. Moreover, $\tilde{T} \equiv T + \frac{1}{n} I$ is a strongly accretive on ∂G , thus $x_{n_k} \rightarrow x_0$, for some $x_0 \in \bar{G}$. Under the hypothesis of (i) T is demicontinuous, $T x_{n_k} \xrightarrow{w} T x_0$. By the continuity of C , we have

$$v_{n_k} = -\frac{1}{n_k} x_{n_k} + \lambda_{n_k} C x_{n_k} \rightarrow \lambda_0 C x_0,$$

for some $v_{n_k} \in T x_{n_k}$. Due to the demiclosedness of T , we have $x_0 \in D(T)$ and $\lambda_0 C x_0 \in T x_0$.

Under the hypothesis of (ii), T is continuous, it is obvious that $\lambda_0 C x_0 \in T x_0$,

Corollary 2. *Let $G \subset X$ be open, bounded with $0 \in G$. Let $T : \bar{G} \rightarrow X$ be bounded, accretive with $T(0) = 0$ and $C : \bar{G} \rightarrow X$ compact. Assume further that $Tx \neq 0$, $x \in \partial G$ and T is ϕ -expansive on ∂G . Let the constant $\alpha > 0$ be such that $\|Cx\| \geq \alpha$, $x \in \partial G$, and satisfy one of the following conditions:*

- (i) X^* is uniformly convex and T is demicontinuous.
- (ii) T is continuous.

Then there exists $(\lambda_0, x_0) \in (0, \infty) \times \partial G$ such that $T x_0 - \lambda_0 C x_0 = 0$.

Proof. The fact that $C : \bar{G} \rightarrow X$ is compact, it is obviously that C is continuous and $C(T + I)^{-1}$ is compact. Since $T : \bar{G} \rightarrow X$ is bounded, it is easy to see that $T(\partial G)$ is bounded. It follows from the proof of Theorem 4, we have that this conclusion holds.

3. Perturbations of maximal monotone operators. In this section, we shall consider analogous results in [12] and [23] with some weaker conditions. The operator $T : X \rightarrow 2^{X^*}$ will be assumed to be maximal monotone. We assume that the space X is a real reflexive locally uniformly convex Banach space with locally uniformly convex dual space X^* . The duality mapping F is now single-valued and bicontinuous.

An operator $T : X \supset D(T) \rightarrow 2^{X^*}$ is monotone if for every $x, y \in D(T)$ and $u \in Tx, v \in Ty$ we have

$$(**) \quad \langle u - v, x - y \rangle \geq 0.$$

A monotone operator T is strongly monotone if 0 in the right-hand side of (***) is replaced by $\alpha \|x - y\|^2$ where $\alpha > 0$ is a fixed constant. A monotone operator T is called maximal monotone if $R(T + \lambda F) = X^*$ for all $\lambda > 0$. An operator $T : X \supset D(T) \rightarrow 2^{X^*}$ is said to be of "type (S_+) " if for every sequence $\{x_n\} \subset D(T)$ with $x_n \xrightarrow{w} x_0 \in X$, and $\limsup_{n \rightarrow \infty} \langle v_n, x_n - x_0 \rangle \leq 0$, for some $v_n \in Tx_n$, we have $x_n \rightarrow x_0$. It is well-known that, under our assumptions on the space X, X^* , the duality mapping F is of type (S_+) on X .

For fundamental properties of monotone operators and other related concepts, the reader can refer to Barbu [1], Barbu and Precupanu [2], Browder [4], Cioranescu [5], Pascali and Sburlan [30], Phelps [32] and Zeidler [34].

For other recent results of this nature, we refer to the papers by Brézis, Crandall and Pazy [3], Guan [9-11], Guan and Kartsatos [12-13] and Kartsatos [23].

The next result improves Theorem 2 of Guan and Kartsatos [12]. There, it was assumed that T m -accretive and A with positively homogeneous of degree $q \in (0, 1]$ and C , positively homogeneous of degree $p \in (1, \infty)$.

Theorem 5. *Let X^* be strictly convex. Let $T : X \supset D(T) \rightarrow 2^{X^*}$ be maximal monotone and strongly monotone at 0 with constant $\alpha > 0$ and $0 \in D(T), 0 \in T(0)$. Let $A, C : \overline{D(T)} \rightarrow X^*$ be completely continuous. Assume further that $\langle Cu, u \rangle \geq 0$ for every $u \in \overline{D(T)}$. Moreover, $\frac{\|Ax_n\|}{\|x_n\|} \rightarrow 0$ for any sequence $\{x_n\} \subset \overline{D(T)}$ with $\|x_n\| \rightarrow \infty$. Then $R(T + A + C) = X$.*

Proof. We want to solve the inclusion

$$Tx + Ax + Cx \ni f,$$

where f is any (but fixed) point in X^* . To this end, we consider the approximate problem

$$(12) \quad Tx + Ax + Cx + \frac{1}{m}Fx \ni f,$$

for every $m = 1, 2, \dots$. Since T is maximal monotone, we can define $R_m = (T + \frac{1}{m}F)^{-1} : X^* \rightarrow D(T)$. Since X is reflexive locally uniformly convex and X^* is strictly convex, the duality mapping F is of type (S_+) . This implies that R_m is continuous [11, Theorem 2.1]. Now, (12) is equivalent to

$$(13) \quad x + R_m(Ax + Cx - f) = 0.$$

Since R_m is continuous and A, C are compact, $R_m(A + C - f) : X^* \rightarrow D(T)$ is compact. By the Leray-Schauder degree theory (see Lloyd [27]), (13) is solvable if we can show that there exists $b > 0$ such that $x + tR_m(Ax + Cx - f) \neq 0$ for any $t \in [0, 1]$, $x \in \partial B_b(0)$. Equivalently, we only need to show that the solutions of $x + tR_m(Ax + Cx - f) = 0$, for any $t \in [0, 1]$, are uniformly bounded. This is certainly true for $t = 0$. If $t = 1$, then (12) is solvable, hence we take $t \in (0, 1)$. Assume that there exist $\{t_n\} \subset (0, 1)$ and $\{u_n\} \subset D(T)$ such that

$$u_n + t_n R_m(Au_n + Cu_n - f) = 0$$

and $\|u_n\| \rightarrow \infty$ as $n \rightarrow \infty$. We have $\frac{1}{t_n}u_n = -R_m(Au_n + Cu_n - f) \in D(T)$, and

$$T\left(\frac{1}{t_n}u_n\right) + \frac{1}{m}F\left(\frac{1}{t_n}u_n\right) + Au_n + Cu_n \ni f,$$

or

$$\frac{1}{m}Fu_n \in -t_n T\left(\frac{1}{t_n}u_n\right) - t_n Au_n - t_n Cu_n + t_n f,$$

which implies

$$\frac{1}{m}\langle Fu_n, u_n \rangle = -t_n^2 \langle v_{t,n}, \frac{1}{t_n}u_n \rangle - t_n \langle Au_n, u_n \rangle - t_n \langle Cu_n, u_n \rangle + t_n \langle f, u_n \rangle,$$

where $v_{t,n} = -\frac{1}{m}F\left(\frac{1}{t_n}u_n\right) - Au_n - Cu_n + f \in T\left(\frac{1}{t_n}u_n\right)$, and we get that

$$\frac{1}{m} \|u_n\|^2 \leq -t_n \langle Au_n, u_n \rangle + t_n \langle f, u_n \rangle,$$

thus

$$\frac{1}{m} \leq -t_n \left\langle \frac{1}{\|u_n\|} \cdot Au_n, \frac{1}{\|u_n\|} \cdot u_n \right\rangle + t_n \left\langle f, \frac{1}{\|u_n\|} \cdot u_n \right\rangle \cdot \frac{1}{\|u_n\|} \rightarrow 0 \text{ as } n \rightarrow \infty.$$

This is a contradiction. Hence, we obtain that (12) and (13) are solvable for any integer m .

Now, we are going to show that all solutions of (12) are uniformly bounded with respect to m . If this is not true, we may assume that there exists $\{w_m\} \subset D(T)$, $Tw_m + Aw_m + Cw_m + \frac{1}{m}Fw_m - f \ni 0$, and $\|w_m\| \rightarrow \infty$ as $m \rightarrow \infty$. Since X is reflexive, we may assume that $\frac{w_m}{\|w_m\|} \xrightarrow{w} w_0$. Since

$$-Aw_m = v_m + Cw_m + \frac{1}{m}Fw_m - f,$$

for some $v_m \in Tw_m$, and thus

$$\begin{aligned} -\langle Aw_m, w_m \rangle &= \langle v_m, w_m \rangle + \langle Cw_m, w_m \rangle + \frac{1}{m} \langle Fw_m, w_m \rangle - \langle f, w_m \rangle \\ &\geq \alpha \|w_m\|^2 - \langle f, w_m \rangle, \end{aligned}$$

which implies

$$-\left\langle \frac{Aw_m}{\|w_m\|}, \frac{w_m}{\|w_m\|} \right\rangle \geq \alpha - \left\langle f, \frac{w_m}{\|w_m\|} \right\rangle \cdot \frac{1}{\|w_m\|} \rightarrow \alpha > 0,$$

as $m \rightarrow \infty$, the left-hand side of the last inequality converges to zero, and we have a contradiction. Therefore, we get that $\{w_m\}$ is bounded.

Now, since X is reflexive, we may assume that $w_m \xrightarrow{w} w_0$, for some $w_0 \in X$. Then $\frac{1}{m}Fw_m \rightarrow 0$ and by our assumptions, $Cw_m \rightarrow Cw_0$, $Aw_m \rightarrow Aw_0$. So, $v_m \rightarrow -Aw_0 - Cw_0 + f$. Since T is maximal monotone and T is demiclosed, hence we have $w_0 \in D(T)$ and $Tw_0 \ni -Aw_0 - Cw_0 + f$ or $Tw_0 + Aw_0 + Cw_0 \ni f$.

We now give Theorem 6 below, which generalizes the main result of Kartsatos in [23, Theorem 7]. Here, we assume that without the assumption that $0 \notin Tx - v^*$, for some $z \in D(T) \cap G$ and some $v^* \in Tz$, and for every $x \in D(T) \cap \partial G$ and without the assumption that $(T + F)^{-1}$ is compact.

Theorem 6. Let $T : X \supset D(T) \rightarrow 2^{X^*}$ be maximal monotone and $C : D(T) \rightarrow X^*$ with $C(T + F)^{-1}$ being compact. Assume, further that $G \subset X$ is open, bounded and such that for some $p \in X^*$, $z \in D(T) \cap G$ satisfying that

$$(14) \quad \langle u + Cx - p, x - z \rangle > 0, \quad (x, u) \in (D(T) \cap \partial G) \times Tx.$$

Then $p \in \overline{(T + C)(D(T) \cap G)}$.

Proof. We want to solve the problem

$$(15) \quad Tx + Cx + \frac{1}{n}Fx \ni p, \quad \forall n \in N,$$

or the equivalently equation

$$(16) \quad u + C(T + \frac{1}{n}F)^{-1}u = p.$$

We may assume that $z = 0 \in D(T) \cap G$ and $0 \in T(0)$. In fact, if this is not true, we consider the new operators \tilde{T}, \tilde{C} defined by

$$\tilde{T}x \equiv T(x + z) - v, \quad \tilde{C}x \equiv C(x + z) + v, \quad x \in D(\tilde{T}) \equiv D(T) - z,$$

where $v \in Tz$. We also set $\tilde{G} \equiv G - z$. It is easy to see that the operator \tilde{T} is maximal monotone on $D(\tilde{T})$. To show the compactness of $\tilde{C}(\tilde{T} + F)^{-1}$, we must show that $\{\tilde{C}(\tilde{T} + F)^{-1}u_n\}$ is a relatively compact set, for any bounded sequence $\{u_n\} \subset X^*$. To this end, let $y_n = (\tilde{T} + F)^{-1}u_n$, by the boundedness of $(\tilde{T} + F)^{-1}$ we have that $\{y_n\}$ is a bounded sequence and

$$\begin{aligned} u_n \in \tilde{T}y_n + Fy_n &= T(y_n + z) - v + Fy_n \\ &= T(y_n + z) + F(y_n + z) - v + Fy_n - F(y_n + z), \end{aligned}$$

that is

$$T(y_n + z) + F(y_n + z) \ni u_n + v + [F(y_n + z) - Fy_n],$$

which implies that

$$y_n + z = (T + F)^{-1}[u_n + v + F(y_n + z) - Fy_n],$$

and

$$\begin{aligned}\tilde{C}(\tilde{T} + F)^{-1}u_n &= \tilde{C}y_n = C(y_n + z) + v \\ &= C(T + F)^{-1}[u_n + v + F(y_n + z) - Fy_n] + v.\end{aligned}$$

By the boundedness of $\{u_n\}$, v , $\{F(y_n + z)\}$, $\{F(y_n)\}$ and the compactness of $C(T + F)^{-1}$, we have $\tilde{C}(\tilde{T} + F)^{-1}u_n$ is a relatively compact set.

If X^* is locally uniformly convex, it is well-known that F is continuous. In order to show that $\tilde{C}(\tilde{T} + F)^{-1}$ is continuous, let $\{u_n\} \subset X^*$ with $u_n \rightarrow u_0 \in X^*$. Since \tilde{T} is maximal monotone and X is locally uniformly convex space, implies that $(\tilde{T} + F)^{-1}$ is continuous [13, Lemma 3.1] and we have

$$y_n \equiv (\tilde{T} + F)^{-1}u_n \rightarrow (\tilde{T} + F)^{-1}u_0 \equiv y_0.$$

Moreover, by the continuity of $C(T + F)^{-1}$, we have that

$$\begin{aligned}\tilde{C}(\tilde{T} + F)^{-1}u_n &= C(T + F)^{-1}[u_n + v + F(y_n + z) - Fy_n] + v \\ &\rightarrow C(T + F)^{-1}[u_0 + v + F(y_0 + z) - Fy_0] + v \\ &= \tilde{C}(\tilde{T} + F)^{-1}u_0,\end{aligned}$$

completing the proof of the compactness of $\tilde{C}(\tilde{T} + F)^{-1}$. To see that (14) is satisfied with $z = 0$, it suffices to observe that

$$\langle (w - v) + C(x + z) + v - p, x \rangle > 0,$$

for every $x \in D(\tilde{T}) \cap \partial\bar{G}$ and every $w \in T(x + z)$. Thus it suffices to prove the theorem with $z = 0$ and $0 \in T(0)$.

Since T is maximal monotone and X is locally uniformly convex, we have $(T + \frac{1}{n}F)^{-1}$ is a continuous mapping on all of X , if $(T + \frac{1}{n}F)$ is denoted by T_0 , then T_0 is a set-valued mapping that maps relatively open (closed) sets in its domain $D(T)$ onto open sets in the space X . For the set $T_0(G \cap D(T))$ is open in X and $T_0(\bar{G} \cap D(T))$ is closed in X [18, Theorem 1]. Hence we have

$$\begin{aligned}
T_0(G \cap D(T)) \cup \partial(T_0(G \cap D(T))) &= \overline{T_0(G \cap D(T))} \\
&\subset \overline{T_0(\bar{G} \cap D(T))} \\
&= T_0(\bar{G} \cap D(T)) \\
&= T_0(G \cap D(T)) \cup T_0(\partial G \cap D(T)),
\end{aligned}$$

which implies that $\partial(T_0(G \cap D(T))) \subset T_0(\partial G \cap D(T))$. Since

$$\overline{T_0(G \cap D(T))} \subset T_0(\bar{G} \cap D(T)) \text{ or } T_0^{-1}(\partial(T_0 G \cap D(T))) \subset \partial G \cap D(T).$$

Now, we consider the homotopy mapping

$$H(t, u) \equiv u + t \left[C \left(T + \frac{1}{n} F \right)^{-1} u - p \right], \quad (t, u) \in [0, 1] \times \overline{T_0(G \cap D(T))}.$$

If we show that $0 \notin H(t, \partial T_0(G \cap D(T)))$, then the Leray-Schauder degree $d(H(t, \cdot), T_0(G \cap D(T)), 0)$ is well-defined, for all $t \in [0, 1]$, because $0 \in T_0(0)$ and the range of the mapping $u \rightarrow C \left(T + \frac{1}{n} F \right)^{-1} u$ on $\overline{T_0(G \cap D(T))}$ is a relatively compact subset of X^* . To show that (15) or (16) is solvable, it suffices to show that $H(t, \cdot)$ has no zero on $\partial T_0(G \cap D(T))$ for any $t \in [0, 1]$. This is certainly true for $t = 0$. Assume that $u_t \in \partial T_0(G \cap D(T))$, for some $t \in (0, 1)$ and let

$$x_t = \left(T + \frac{1}{n} F \right)^{-1} u_t \in \partial G \cap D(T).$$

Then

$$(17) \quad T x_t + t C x_t + \frac{1}{n} F x_t \ni t p.$$

However we shall show that (17) does not hold by showing that

$$(18) \quad \langle v_t + t(C x_t - p), x_t \rangle > 0,$$

for some $v_t \in T x_t$, for all $t \in (0, 1)$. If $\langle C x_t - p, x_t \rangle \geq 0$, then our assertion is trivially true. Let $\langle C x_t - p, x_t \rangle < 0$, by our assumption

$$\langle v_t, x_t \rangle > -\langle C x_t - p, x_t \rangle > -t \langle C x_t - p, x_t \rangle,$$

and

$$\langle v_t + t(Cx_t - p), x_t \rangle > 0.$$

Combine the inequalities (17) and (18), we get the contradiction:

$$\frac{1}{n} \|x_t\|^2 \leq \frac{1}{n} \|x_t\|^2 + \langle v_t + t(Cx_t - p), x_t \rangle = 0.$$

Thus, $H(1, u) = 0$ is solvable with solution $u \in \overline{T_0(G \cap D(T))}$, i.e., $Tx + Cx + \frac{1}{n}Fx \ni p$ is solvable with solution $x_n \in \bar{G} \cap D(T)$. Since $\bar{G} \cap D(T)$ is bounded, we have $p \in \overline{(T + C)(D(T) \cap \bar{G})}$.

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